



Operation manual

KDE200 Series

Smart general Universal Inverter



Preface

Thank you very much for choosing KDE200 series high-performance universal converter. This manual can provide you with the detailed rules and precautions, including installation, wiring, the setting of functional parameter, daily maintenance, malfunction diagnosis and solution etc.

To give full play to its function and ensure the safety of both users and product, please read this manual carefully before using it. Any incorrect operations may lead to fault, malfunction or shortened lifetime, even damage of device and accident casualty.

Please pay attention to the following points when using it:

- Power must be shut off before wiring
- Ground wire must be connected correctly
- In any case, AC power lines can't be connected to the output terminals, such as U, V or W
- Do not touch the internal components for safety
- Only the qualified electronic engineer is allowed to assemble, wire, repair or maintain the converter
- Converter must be installed in a appropriate operating environment and far away from humidity or water drops; care must be taken to prevent it from direct sunlight or being overheated
- Do not conduct the procedure of inspection or maintenance until converter has been shut down for more than 3 minutes
- No permission is granted to change or modify the internal components or circuits.
- Do not conduct the Withstand Voltage Test on the internal components
- This product can't be applied in the situation that may endanger personal safety

This manual is enclosed randomly as an attachment, please keep it safe in case that you need it for the inspection or maintenance of this product. Any information in this manual is subject to change without notice in accordance with our policy of continuous improvement of product.

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Chapter 1 Acceptance

1-1 Inspection on Delivery

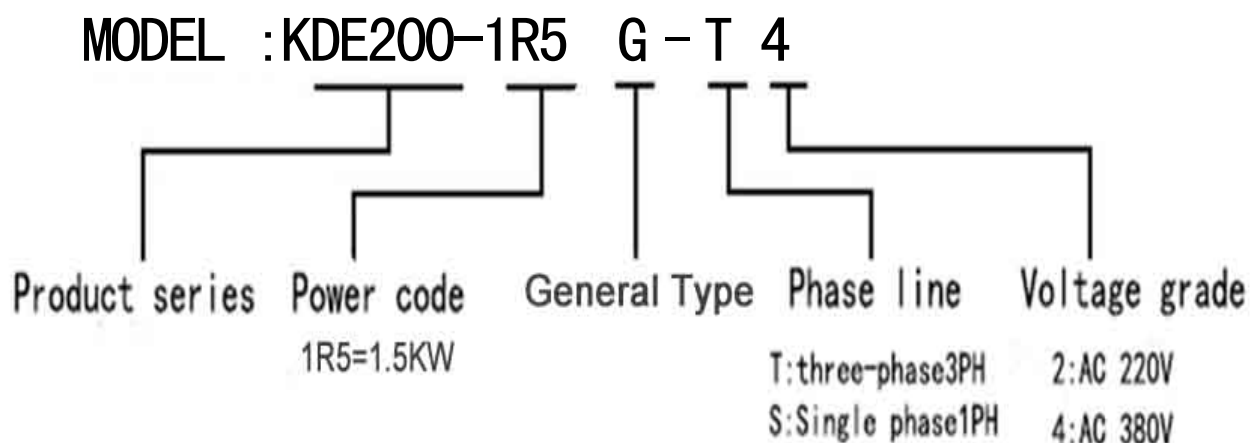
Pre-delivery inspection for each converter will be implemented strictly by our QC Department; meanwhile, the packaging will be strengthened with special packing materials which can protect it from damage caused by collision. Please find the following points to check after unpacking it:

- Please check if there is any damage caused during the transportation;
- Please check if the enclosed documents are all inside the case, including manual, certificate and warranty card
- Please check if this is the model of the product for which you placed an order
- Please check whether you receive the right converter accessories you ordered

1-2 Illustrations for Nameplate

Product model	⇒	MODEL: KDE200-1R5GT4
Power	⇒	POWER: 1.5KW
Input power specification	⇒	INPUT: 3PH 380V \pm 15% 50/60HZ
Output power specification	⇒	OUTPUT: 0-380V 0-400HZ 3.8A
		BAR CODE
Item number	⇒	SER NO: 1 1 5 0 5 0 0 0 1

Illustrations for Product Model



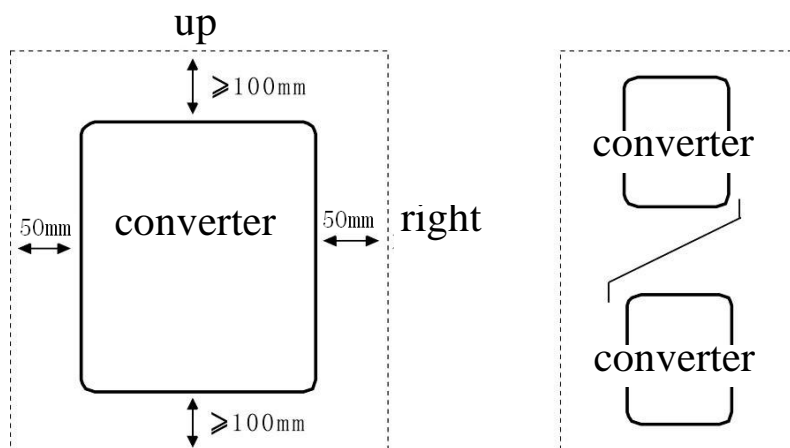
Chapter 2 Installation

2-1 Installation environment

- No Water drops, steam, dust or oily dust surrounded
- No caustic or inflammable gas and liquid surrounded
- No floating dust and metal particles surrounded
- Solid base without vibration
- No electromagnetic or noise interference
- Ambient temperature should be $-10^{\circ}\text{C} \sim +40^{\circ}\text{C}$; in case that the ambient temperature is higher than 40°C and that it is overheated, it should be stored in a place where there is good ventilation

2-2 Installation Instructions and Space Limit

- It should be installed on the fire-proof frame, for example metal frame, in case that it causes fire accidents
- It should be mounted by screws vertically; upside-down, slant or horizontal mounting are not allowed
- Spare space must be ensured for the ventilation of converter in case that it's overheated while it's running
- Ventilation must be taken into consideration to ensure that ambient temperature is lower than specified value when converter is installed inside a control cabinet
- To minimize the heat effect on each other, they should be horizontally installed abreast if two or more converters are installed in the same control cabinet; Baffle plate must be set up between them for the same reason if they have to be installed vertically
- It should be kept away from various impurity, such as fiber, paper scraps, wood chips or metal filings

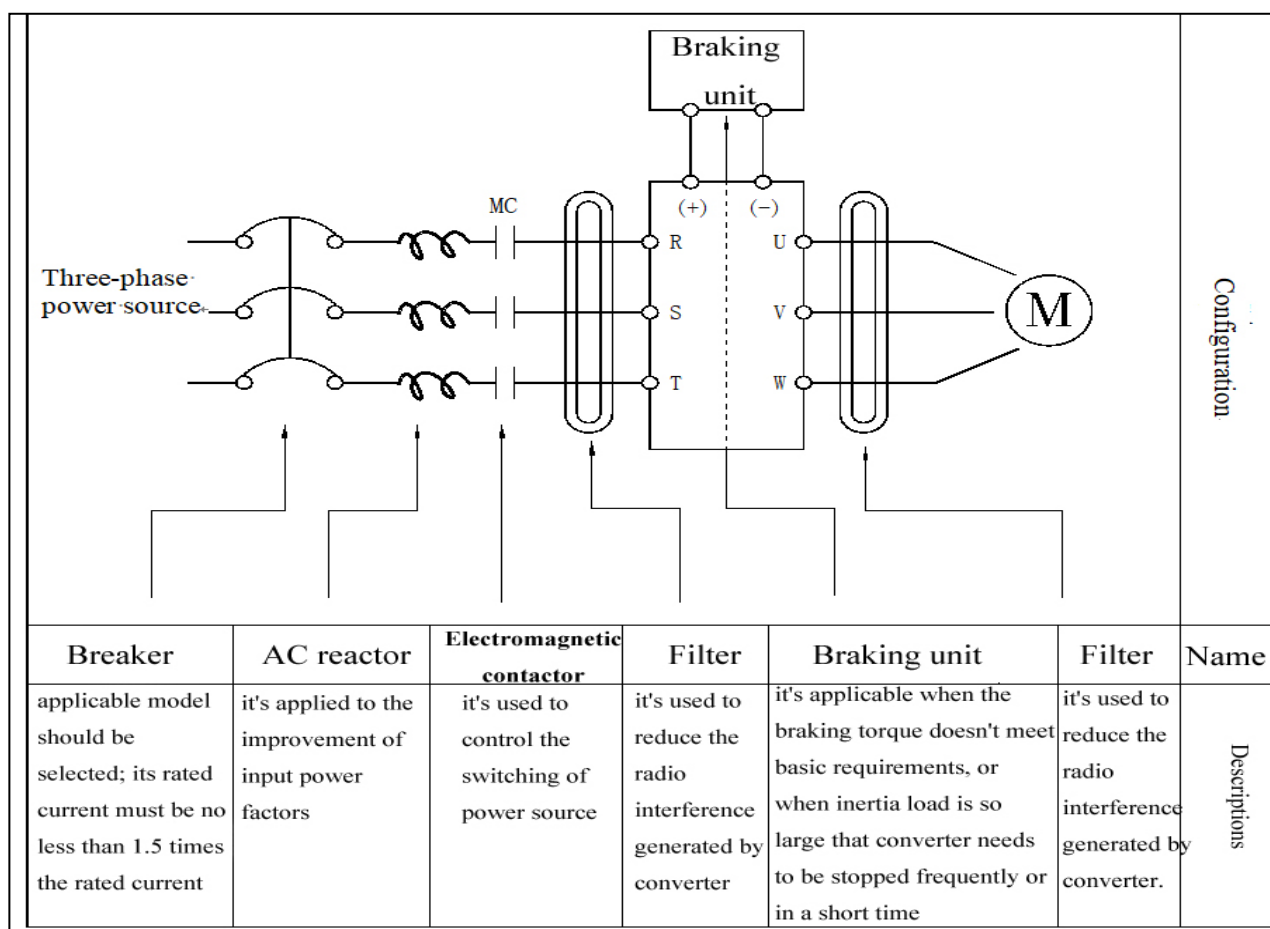


Chapter 3 WIRING

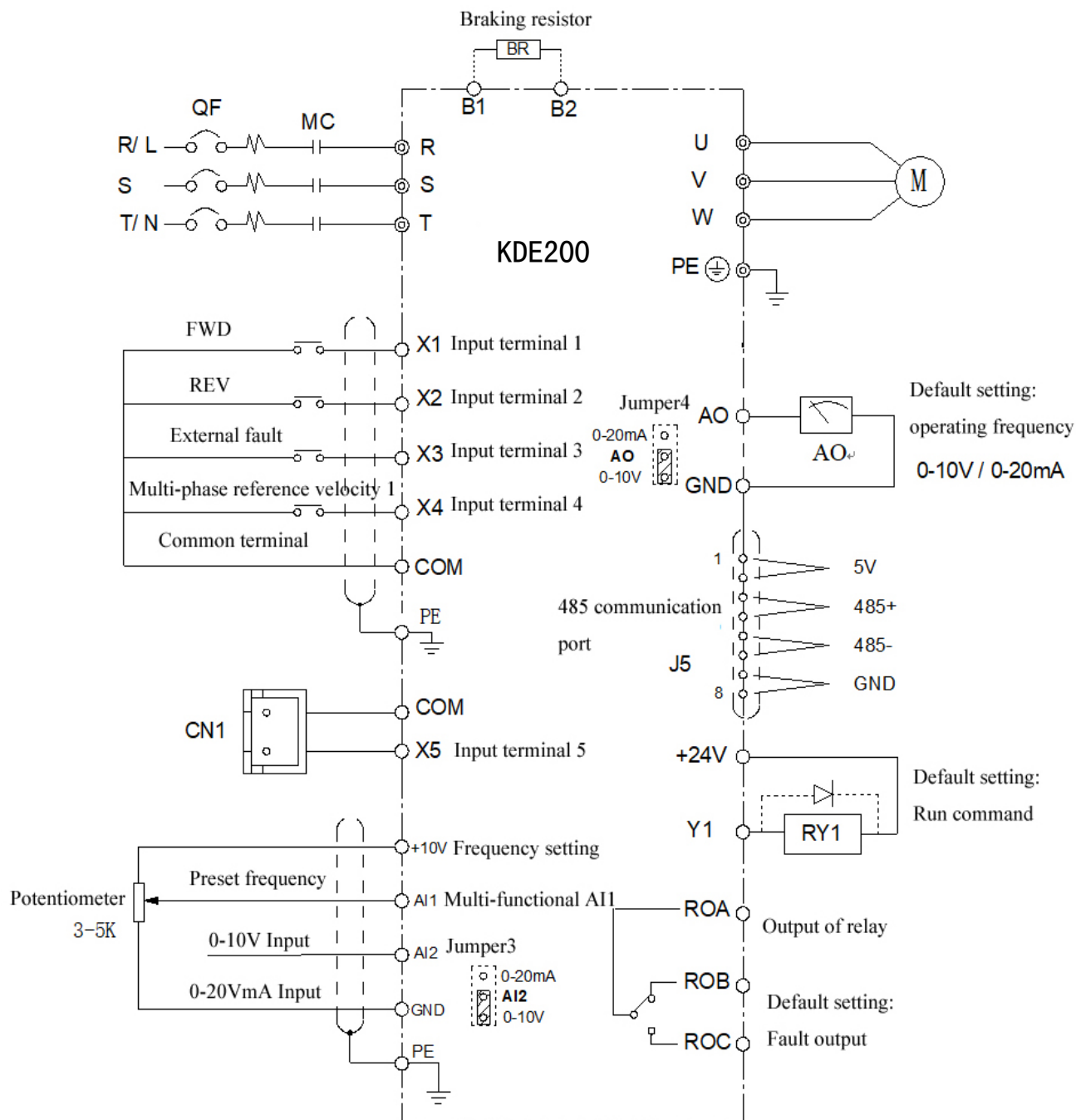
(For the safety of operator as well as devices, only the qualified electronic engineer is allowed to operate it. Please pay attention to the following precautions while wiring:)

- Power must be shut off before wiring
- PE earth terminal must be connected with the ground
- The rated voltage must be in conformity with AC voltage
- Power cords must be connected with the terminal R, S and T while lines for motor should be connected with terminal U,V and W; any incorrect connection may cause damage to the internal components of converter
- The reliability of the terminals and wires must be evaluated before wiring, and screws for the terminals of major loop must be fastened solidly.
- To avoid electric shock, do not touch the terminals of major loop


3-1 Connection Methods for Assorted Devices



3-2 andard Wiring Diagram



3-3 Description of Major Loop's Terminal

Terminal symbol(code)	Functional Descriptions
R, S, T	Terminals for three-phase AC input 380V
L,N	Terminals for Single-phase AC input 220V
U, V, W	output terminals, connect with three-phase AC electromotor
B1, B2	terminals for braking resistor(optional)
(+), (-)	terminals for external braking unit(optional)
	Terminal of ground (Earth terminal)

For safety's sake, please connect wires according to the regulations of National Electrical Code while proceeding wiring

3-3-1 Connection of input terminal R, S, T or L,N

An additional breaker/chopper must be connected in series with the terminals of major loop(R,S,T or L,N) and three-phase AC or Single-phase AC input. For better running, an electromagnetic contactor should be connected with them in series so that it could cut off the power while the protection function of converter is activated (Tip: R-C surge absorbers should be added to the ends of electromagnetic contactor.

If an additional earth leakage circuit breaker(ELCB) is installed as a protective device for electric leakage, the sensitivity of current should be more than 200mA while actuation time should be no less than 0.1 second in order to prevent ELCB from malfunctioning.

AC reactor must be connected with the input terminals in case that some of rectifiers are damaged by high-voltage and high-current input circuit from the grid, which could also improve the power factors of input terminals.

Do not control the converter by adopting the way of powering on or off major loop. Instead of that, RUN/STOP buttons on the keyboard or control loop terminals should be applied to the control of converter; if it has to be controlled by that way, it can be implemented only once every one hour.

It's feasible to reduce the interference with devices nearby by connecting an additional noise filter with the input terminals.

Do not connect converter driven by three-phase power to single-phase source.

3-3-2 Connection of output terminal U,V,W

Output terminals must be connected to three-phase motor in the correct order; if motor rotates in the wrong direction, any two wires among U, V and W electrical wiring can be switched with each other.

In any case, do not connect output terminals to phasing capacitor or surge absorber.

When the length of wire connecting converter with motor is more than 50 meters, there may be a large amount of electric leakage caused by the capacitors between the wiring, which may lead to over current; additionally, to protect the insulation of motor from being damaged, an additional output reactor must be installed.

An additional noise filter can be installed to reduce the electromagnetic interference of output if surroundings can be easily affected by converter; interference can also be minimized by reducing its carrier frequency.

3-3-3 Connection of braking resistors and braking unit

If inertia load is so large that converter needs to be shut off frequently or in a short time, braking resistors or braking unit should be selected and installed accordingly to solve the issue of insufficient braking capacity or lengthen braking torque.

Terminals(B1, B2) of major loop must be connected with braking resistors(Tip: terminal B1 or B2 indicates that this converter is the one with built-in braking units)

If there is no built-in braking unit, positive(+) and negative(-) terminals of major loop should be connected to external braking units.

Do not connect positive(+) and negative(-) terminals of major loop to braking resistor.

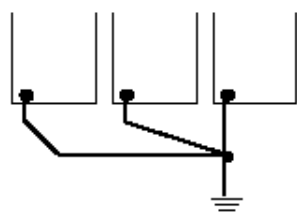
3-3-4 Earth terminal PE

For safety's sake, earth terminal PE must be well grounded in order to reduce noise.

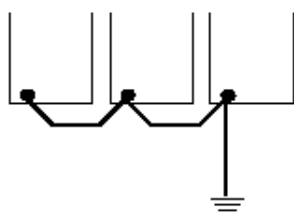
Please use the standard ground lead which should be as short and thick as possible(its grounding impedance should be no more than 10Ω)

Do not connect its ground lead with that of high-current loading machine to ground at the same time, for example welder or high-power motor, they must be grounded separately.

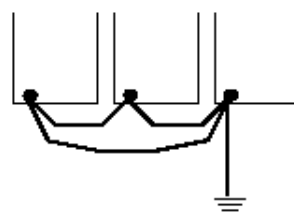
All the converters must be connected to the same earth terminal directly if two or more converters are installed together; please refer to the wiring layout below:



(a) correct



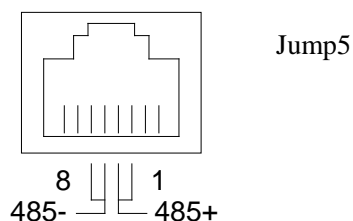
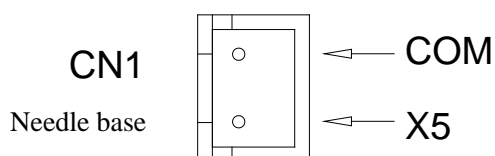
(b) not recommend



(c) error

3-4 Explanations of control loop terminals

10V	AI1	AI2	GND	AO	24V	Y1	COM	X1	X2	X3	X4	ROA	ROB	ROC
-----	-----	-----	-----	----	-----	----	-----	----	----	----	----	-----	-----	-----



Items	symbol	Terminal name	Terminal description and default setting
Multi-functional Input	X1	Multi-functional Input Terminal 1	default setting: Forward /Stop
	X2	Multi-functional Input Terminal 2	default setting: Reverse /Stop

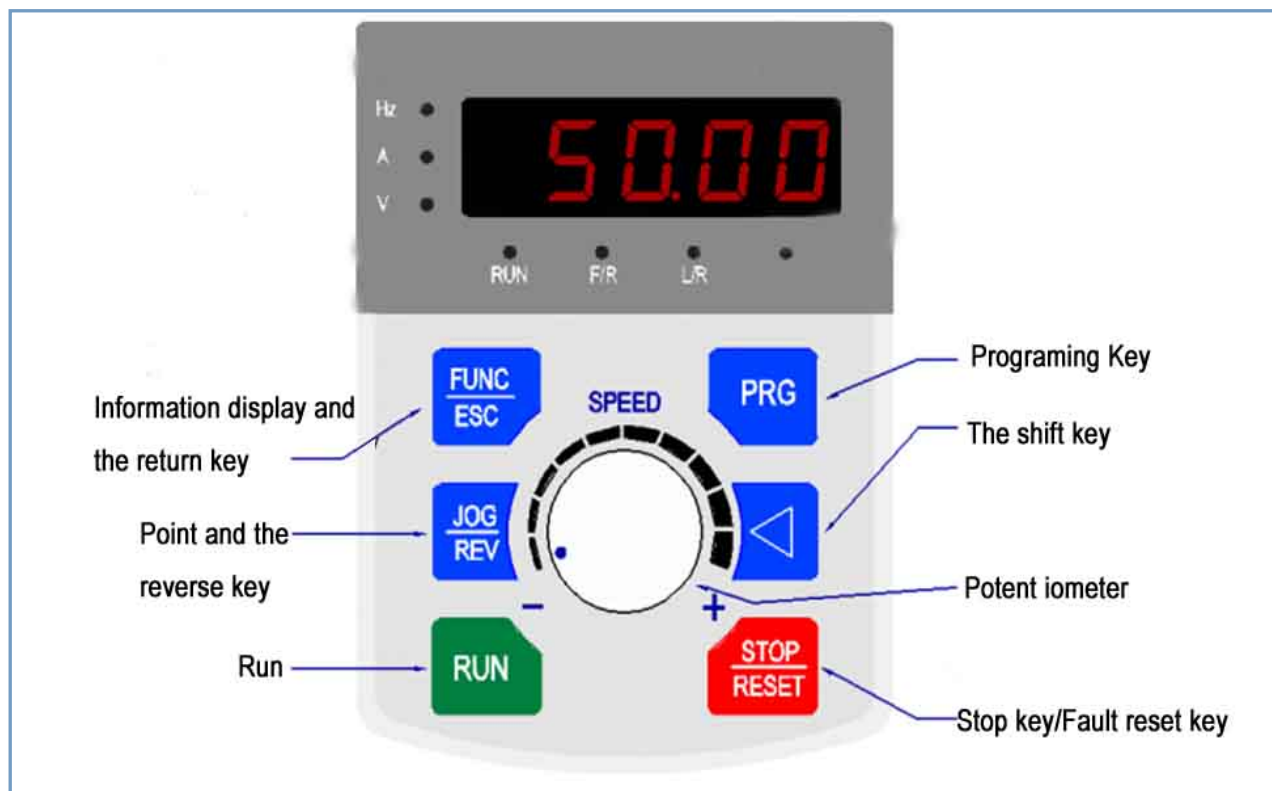
	X3	Multi-functional Input Terminal 3	default setting: external fault input
	X4	Multi-functional Input Terminal 4	default setting: Multi-step & speed reference 1
	X5	Multi-functional Input Terminal 5	default setting: Multi-step & speed reference 2
	COM	Common terminal	Multi-functional input common terminal, +24V power reference ground
analog input	AI1	analogue input 1	0~10V input
	AI2	analogue input 2	0~10V/0~20mA input (J4 jumper is optional)
	+10V	Analogue preset power source	+10V DC 10mA (potentiometer 3~5K)
	GND	analogue reference ground	analogue input, output reference ground
Multi-functional output	Y1	Multi-functional output Terminal 1	default setting: running status
	ROA	Relay output ROA-ROB (normally closed) ROA-ROC (normally opened)	default setting: fault output
	ROB		
	ROC		
analogue output	AO	analogue output terminal	0~10V/0~20mA output (J5 jumper is optional) GND is also known as reference ground
Power source	+24V	+24V power source	+24V DC 100mA COM is also known as power ground
communication	485+	485 signal positive terminal	Standard serial communication interface RS-485; Please use twisted-pair or shielded line
	485-	485 signal negative terminal	

Multi-core shielded cable or stranded wire should be used to connect and control terminals. The terminal which is closed to converter must be connected to earth terminal PE while shielded cable is applied to it. When wiring, control cable must be kept away from main circuit and high-current circuit at least 20cm, such as power lines, motor wires, wires for contactor and relay. Instead of parallel wiring, vertical wiring should be adopted to prevent converter from malfunction resulted from external interference.

Chapter 4 Keyboard & Panel

4-1 Illustrations of Keyboard

4-1-1 Diagram of Keyboard



4-1-2 Indicator light show

1) Functional indicator light:

Light is the name of the	Indicator light show
RUN	Running status indicator light: When the lights went out said inverter in the down state; Light flash frequency converter in the parameter self learning state; When the light is said inverter in the running state
F/R	And reversing lamp: Said the lights went out in the forward state; The light is said in a state of inversion.
L/R	External terminal control indicator: Said the lights went out the keyboard control state; The light is said terminal control state.

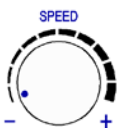

2) Unit indicator light shows:

Light is the name of the	Indicator light show
Hz	Frequency unit
A	Current unit
V	Voltage unit

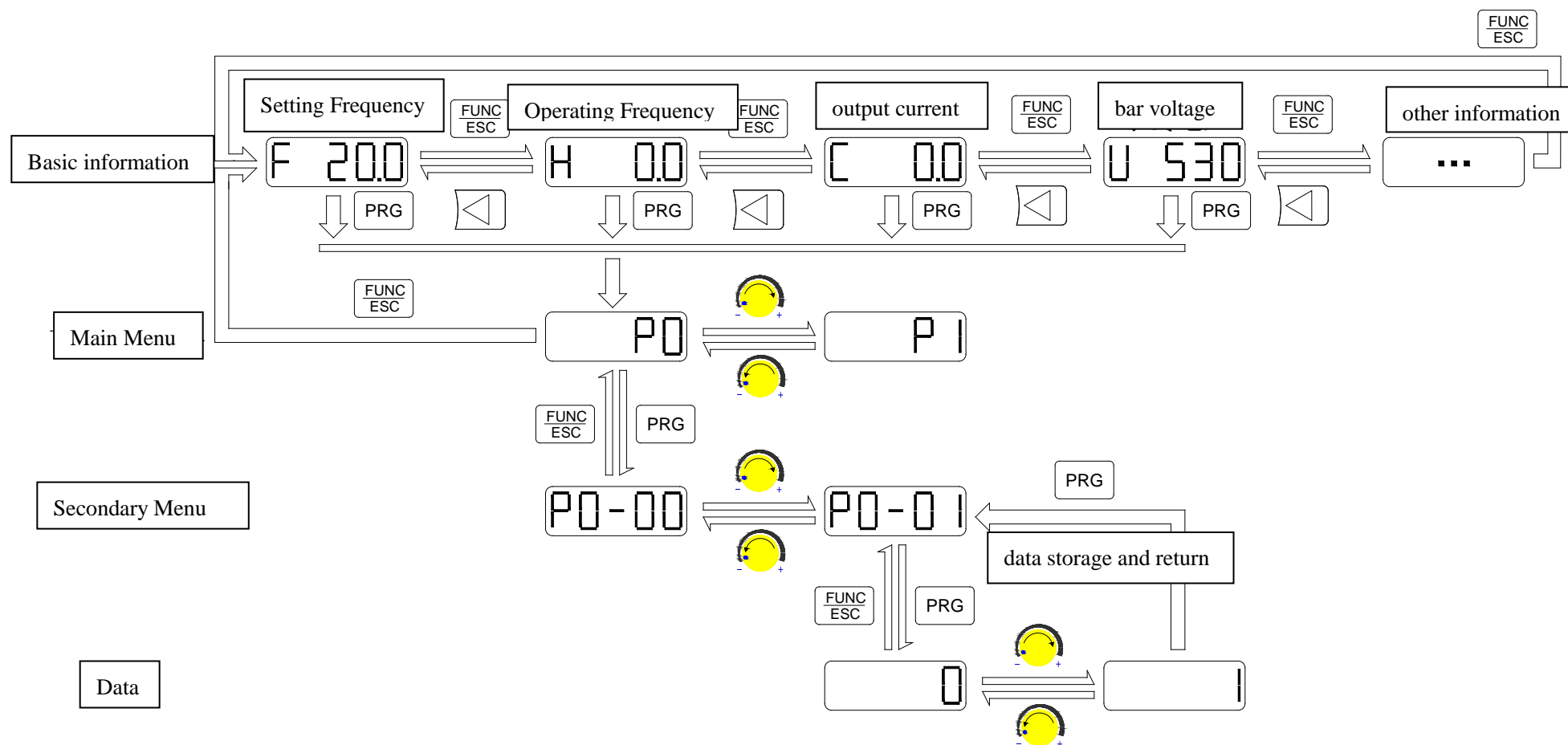
3) Digital display area:

Five LED display, can display setting frequency, output frequency and so on all sorts of monitoring data and alarm code.

3 Keys function description

The key symbol	The name says	Functional specifications
PRG	Programming key	Enter the menu programming; Parameter setting for confirmation.
FUNC/ ESC	Return key	Under the outage display and operation interface, recycled display status information; Return to the superior programming menu.
	Potentiometer multifunction button	Clockwise rotation: frequency, function code, data increasing
		Counter clockwise rotation: frequency, function code, data decrease
		Middle press: select the function code or confirm the data
	Shift key	The display status information can be displayed at the interface and the running display interface, and the modification parameters can be selected.
RUN	The operation key	Under the keyboard operation, used to run the operation.
STOP/ RESET	Stop/reset button to	Running state, press this button can be used to stop operation, the restriction of the function code P0-02; Fault alarm state, can use the key to copy a failure.
JOG/ REV	Point move / forward / reverse key	The key function by function code P1-03 determine: 0: inching operation 1: forward reversal switch for positive & negative switching key.

4-2 Illustrations of Keyboard Operation



Chapter 5 Running


5-1 Commissioning

5-1-1 Check Before Running

- Please check whether wiring is correct or not, especially output terminals(U, V, W) which mustn't be connected to power source; additionally, earth terminals PE must be well grounded as well.
- Please confirm that there is no short circuit or line-to-ground short circuit between terminals or any exposed charged component.
- Please confirm that all the components are fastened, such as terminals, pluggable connectors or screws.
- Make sure that all the switches are off before it's connected to power source, and that converter will not malfunction or be started when it's switched on.
- Do not connect it to power s until its enclosure is assembled.

5-1-2 Commissioning


Converter must be checked and confirmed comprehensively before commissioning; its default running mode is to be controlled through keyboard and panel.


- Please push the button  and check the following points (its default jog frequency is 5.0 HZ):

Whether motor is rotating in the right direction or not;

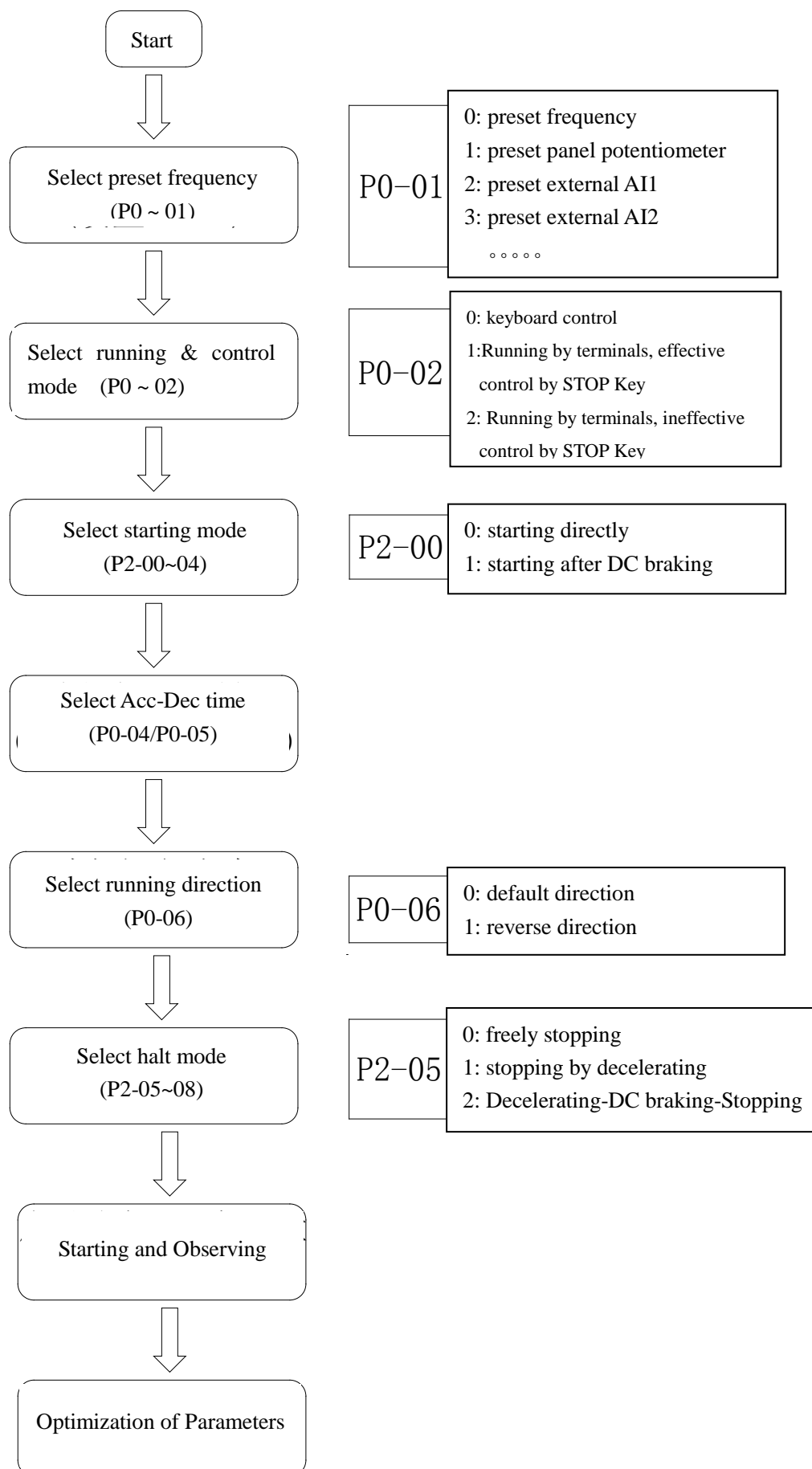
Whether its rotation is smooth or not(NO abnormal noise or vibration is permitted)

Whether the acceleration or deceleration of motor is stable.

- If converter functions properly, please preset its operating frequency first; please press the  to start commissioning and check whether its output current/voltage is normal or not; only after confirmation can it be power-on.

Converter must be switched off immediately by pushing the button  if there is anything goes wrong with converter or motor; meanwhile, please refer to Chapter 7 Fault Correcting to find out the reason why it malfunctions. Even it is shut off, output terminals(U, V, W) may still cause electric shock to anyone who touches them unless power ports(R, S, T) are disconnected from main circuit. Additionally, it will take some times for filter capacitor to discharge because there is still charging voltage stored in the filter capacitor even main power source is shut off. Charging indicator will be off if main power source is shut off; voltage in the middle DC circuit must be tested by voltmeter. Only after it's confirmed that the voltage is lower than specified value can internal circuit be touched.

5-2 Quick Debugging/Quick set up instructions



Chapter 6 Specification of Functional Parameters

6-1 Functional Parameters Table

P0: Basic functional parameters

Function Code	Description	Description and Range	Default	Modification
P0-00	Parameter setting mode	0: Enabled (except those parameters marked with "×") 1: Disabled (except P0-00) 99: Factory reset	0	●
P0-01	Frequency setting mode	0: Frequency setting (UP/DOWN) 1: Panel potentiometer 2: External AI1 3: External AI2 4: PI regulation 5: UP/DOWN by the P5-20 add and subtract 6: UP/DOWN by the P5-20 add and subtract, frequency clear to zero	0	●
P0-02	Control mode for running	0: Controlled by keyboard 1: Controlled by terminals, STOP Key disabled 2: Controlled by terminals, STOP Key enabled	0	●
P0-03	Frequency setting	0.0 Hz ~Upper limiting frequency (P0-09)	50.0Hz	○
P0-04	Acceleration time 0	0.1s~3600.0s	20.0s	○
P0-05	Deceleration time 0	0.1s~3600.0s	20.0s	○
P0-06	Running direction Option	0: Default direction 1: Reverse direction	0	●
P0-07	Anti-reversion Setting	0: Enabled 1: Disabled	0	●
P0-08	Maximum frequency	Upper limit frequency (P0-09) ~400.0Hz	60.0 Hz	●
P0-09	Upper limiting frequency	Lower limiting frequency (P0-10) ~Maximum frequency (P0-08)	50.0Hz	●
P0-10	Lower limiting frequency	0.0Hz~Upper limiting frequency (P0-09)	0.0Hz	●

P0-11	Jog frequency	0.0Hz~Upper limiting frequency (P0-09)	5.0Hz	○
P0-12	Carrier frequency	1~16KHz	Depend ing on model	●
P0-13	Carrier frequency Regulation	0: Regular PWM mode 1: Random PWM mode	0	●
P0-14	Keyboard frequency setting (UP/DOWN)	0: Automatic storage when power down 1: No storage for power-down	0	○

(P0-15~ P0-17Reserved)

P1: Human Interface parameters

Function Code	Description	Setting range	Default	Modification
P1-00	Default display information for Starting	0: Setting frequency 1: Output frequency 2: Output current 3: Bus voltage 4: Rotational Speed of motor 5: Percentage of output current 6: IGBT temperature 7: Output voltage 8: Output power 9: Count value 10: PI index value 11: PI feedback value 12: Accumulated running time (hour) 13: Input terminal status 14: Output terminal status 15: Power	0	O
P1-01	Setting of display information	0: 0~3 messages 1: 0~7 messages 2: 0~11 messages 3: 0~15 messages	1	O
P1-02	Display coefficient of mechanical speed	0.1~60.0	29.0	O

P1-03	JOG/REV (function selector)	0: Jog 1: FDW/REV switching	0	●
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(P1-04~ P1-06 Reserved)

P2: Parameters of Start-Stop Mode

Function Code	Description	Setting range	Default	Modification
P2-00	Starting Mode	0: Starting directly 1: DC braking-Starting 2: Speed tracking after startup 3: Adaptive direction of speed tracking	0	●
P2-01	Starting frequency	0.0~10.0Hz	0.5 Hz	●
P2-02	Retention time for starting	0.0~50.0 s	0.0s	●
P2-03	Braking current before starting	0~150.0%	50.0%	●
P2-04	Braking time before starting	0~50.0s	0.0s	●
P2-05	Stop mode	0: Regular stopping 1: Stop by decelerating 2: Decelerating-DC braking-Stopping	1	●
P2-06	Start frequency of DC braking	0.0~10.0Hz	0.0Hz	●
P2-07	Braking current for stopping	0~150.0%	50.0%	●
P2-08	Braking time for stopping	0~50.0s	0.0s	●
P2-09	FWD/REV Dead time	0.0~50.0 s	0.0s	●
P2-10	Lower limiting frequency for running control	0: running with lower limiting frequency 1: stopping 2: standby	0	●

(P2-11~ P2-12 Reserved)

P3: Parameters of Motor

Function	Description	Setting range	Default	Modification
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Code				
P3-00	Rated frequency	F3 (P4-05) ~400.0Hz	50.0Hz	●
P3-01	Rated voltage	200~440V	Depending on model	●
P3-02	Rated current	0.1~999.9A	Depending on model	●
P3-03	Rated power	0.1~630.0KW	Depending on model	●
P3-04	Rated rotational Speed	1~36000rpm	1440rpm	●
P3-05	No-load current	0.1~999.9A	Depending on model	●
P3-06	Stator resistance	0.001~50.000Ω	Depend on model	●
P3-07	Excitation/Magnetic inductance	0.1~5000.0mH	Depend on model	●

(P3-08~ P3-12 Reserved)

P4: V/F Control Parameters

Function Code	Description	Setting range	Default	Modification
P4-00	V/F curve setting	0: General V/F 1: 2 power V/F 2: 3 power V/F 3: high starting torque V/F 4: Self-setting V/F 5: Self-adaptive control	0	●
P4-01	V/F Intermediate frequency 1	0.0Hz~ F2 (P4-03)	5.0Hz	●
P4-02	V/F Intermediate voltage1	0~ rated voltage (P3-00)	38V	●
P4-03	V/F Intermediate frequency 2	F1 (P4-01)~F3 (P4-05)	25.0Hz	●
P4-04	V/F Intermediate voltage 2	0~ rated voltage (P3-00)	190V	●
P4-05	V/F Intermediate	F2 (P4-03)~rated frequency (P3-00)	50.0Hz	●

	frequency 3			
P4-06	V/F Intermediate voltage 3	0~ rated voltage (P3-00)	380V	●
P4-07	Torque upgrade	0.0~15.0%	0	●
P4-08	Slip compensation	0.0~10.0Hz	0.0 Hz	●
P4-09	AVR function	0: Disabled 1: always enabled 2: only enabled in process of deceleration	1	●
P4-10	Energy-efficient running	0: Disabled 1: Enabled	0	●

(P4-11~ P4-18 Reserved)

P5: Input function parameters

Function Code	Description	Setting range	Default	Modification
P5-00	AI1 lower limiting value	0~10.00V	0.00V	○
P5-01	Corresponding setting for AI1 lower limit	0~100.0%	0.0%	○
P5-02	AI1 upper limiting value	AI1 lower limiting value~10.00V	10.00V	○
P5-03	Corresponding setting for AI1 upper limit	0~100.0%	100.0%	○
P5-04	AI1 input filtering time	0.0s~10.0s	0.1s	○
P5-05	AI2 lower limiting value	0.00V~10.00V	0.00V	○
P5-06	Corresponding setting for AI2 lower limit	0~100.0%	0.0%	○
P5-07	AI2 upper limiting value	AI2 lower limiting value~10.00V	10.00V	○
P5-08	Corresponding	0~100.0%	100.0%	○

	setting for AI2 upper limit			
P5-09	AI2 input filtering time	0.0s~10.0s	0.1s	○
P5-10	Multi-functional Input Terminal X1	0: Disabled 1: Forward 2: Reverse 3: Three-wire control 4: Multi-phase reference velocity 1 5: Multi- phase reference velocity 2 6: Multi- phase reference velocity 3 7: JOG forward 8: JOG reverse 9: Increasing frequency 10: Decreasing frequency 11: Acc-Dec time Option 1 12: Acc-Dec time Option 2 13: Stop of Acc/Dec 14: External fault Input 15: Fault reset 16: Regular stopping 17: External count value input 18: count clear 19: program run 20: pause of program run	1 Forward	●
P5-11	Multi-functional Input Terminal X2		2 Reverse	●
P5-12	Multi-functional Input Terminal X3		14 Fault	●
P5-13	Multi-functional Input Terminal X4		4 reference velocity 1	●
P5-14	Multi-functional Input Terminal X5 (CN1 needle base input)		5 reference velocity 2	●
P5-15	Multi-functional Input Terminal X6		Reserved	●
P5-16	Multi-functional Input Terminal X7		Reserved	●
P5-17	Multi-functional Input Terminal X8		Reserved	●
P5-18	Terminal control mode	0: Two-wire control mode 1 1: Two-wire control mode 2 2: Three-wire control mode 1 3: Three-wire control mode 2	0	●
P5-19	Terminal filtering time	2ms~100 ms	10 ms	○
P5-20	The range of the UP/DOWN increasing decline	0.0~50.0Hz	0.1	○

(P5-20~ P5-30 Reserved)

P6: Output function parameters

Function	Description	Setting range	Default	Modification
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Code				
P6-00	Y1 output options	0: Disabled 1: Running 2: Direction 3: Fault output 4: On standby 5: Frequency received 6: FDT 7: Upper limiting frequency received 8: Lower limiting frequency received 9: Setting count value received 10: Designated count value received	1	○
P6-01	Y2 output options		2	○
P6-02	Relay output options		3	○
P6-03	AO1 options	0: Operating frequency 1: Output current 2: Bus voltage 3: Output voltage	0	○
P6-04	AO1 correction coefficient	0.0~250.0%	100.0%	○
P6-05	Stop delay time setting	0~3000.0S	0	○

(P6-05~ P6-08 Reserved)

P7: PI control parameters

Function Code	Description	Setting range	Default	Modification
P7-00	PI preset source options	0: Digital keyboard 1: Panel potentiometer 2: Analog channel AI1 3: Analog channel AI2	0	○
P7-01	PI set value	0.00~10.00 V	0.00V	○
P7-02	PI feedback source options	0: Analog channel AI1 1: Analog channel AI2	0	○
P7-03	PI output characteristics options	0: Positive 1: Negative	0	○
P7-04	Proportional gain (P)	0.0~10.0	0.1	○

P7-05	Integral time (I)	0.0~100.0s	0.1s	○
P7-06	Deviation limit	0.00~2.00	0.10	○
P7-07	Sampling period(T)	0.1~100.0s	0.5s	○
P7-08	Detected value of feedback disconnection	0.00~5.00	0.10	○
P7-09	Time for detecting feedback disconnection	0.0~100.0s	1.0s	○
P7-12	Sleep time	0~3000S	600	○
P7-13	Dormancy pressure	0~10.00	0	○
P7-14	Dormancy frequency	0~50.0Hz	0	○
P7-15	Wake up the pressure	0~10.00	0	○

(P7-10~ P7-15 Reserved)

P8: Simple PLC and Multispeed Parameters

Function Code	Description	Setting range	Default	Modification
P8-00	Program run mode	0: Disabled 1: Program stop after one cycle of running 2: Program operates as last program runs after one cycle of running 3: Circulatory running of program	0	●
P8-01	First phase speed	Lower limiting frequency ~ Upper limiting frequency	0.0Hz	○
P8-02	Second phase speed	Lower limiting frequency ~ Upper limiting frequency	0.0Hz	○
P8-03	Third phase speed	Lower limiting frequency ~ Upper limiting frequency	0.0Hz	○
P8-04	Forth phase speed	Lower limiting frequency ~ Upper limiting frequency	0.0Hz	○
P8-05	Fifth phase speed	Lower limiting frequency ~ Upper limiting frequency	0.0Hz	○
P8-06	Sixth phase speed	Lower limiting frequency ~ Upper limiting frequency	0.0Hz	○

		frequency		
P8-07	Seventh phase speed	Lower limiting frequency ~ Upper limiting frequency	0.0Hz	O
P8-08	Runtime of principal frequency	0~6400.0	0.0	O
P8-09	First phase time	0~6400.0	0.0	O
P8-10	Second phase time	0~6400.0	0.0	O
P8-11	Third phase time	0~6400.0	0.0	O
P8-12	Forth phase time	0~6400.0	0.0	O
P8-13	Fifth phase time	0~6400.0	0.0	O
P8-14	Sixth phase time	0~6400.0	0.0	O
P8-15	Seventh phase time	0~6400.0	0.0	O
P8-16	Time unit of multi-velocity	0: second 1: minute 2: hour	0	●
P8-17	Running directions of programs	0~255 BIT 0~7 indicates 0~7 directions (0: Forward 1: Reverse)	0	●
P8-18	Timing for each program's Acc-Dec	0~65535 BIT0~15 indicates Acc-Dec time of 0~7 phase	0	O

(P8-19~ P8-20 Reserved)

P9: Protection Function parameters

Function Code	Description	Setting range	Default	Modification
P9-00	Options for overload protection	0: Disabled 1: Enabled	0	●
P9-01	Critical point of overload protection	50~120%	110%	●
P9-02	Overvoltage protection	0: Disabled 1: Enabled	1	●
P9-03	Critical point of Overvoltage	110.0~150.0%	125	●

P9-04	Over-current protection	0: Disabled 1: Enabled	1	●
P9-05	Critical point of over-current	100~180%	150	●
P9-06	Phase-failure protection of input	0: Disabled 1: Enabled	0	●
P9-07	Phase-failure protection of output	0: Disabled 1: Enabled	0	●
P9-08	Latest fault information	0~20		×
P9-09	Last fault information	0~20		×
P9-10	Last two fault messages	0~20		×
P9-11	Operating frequency of latest fault			×
P9-12	Output current of latest fault			×
P9-13	Bus voltage of latest fault			×
P9-14	Input state of latest fault			×
P9-15	Output state of latest fault			×
P9-16	Fault since the reset function	0: invalid 1: under-voltage fault alarm automatic reset (unlimited) 2 ~ 20: fault self-recovery	0	●

(P9-16~ P9-17 Reserved)

Parameters of PA Enhancements

Function Code	Description	Setting range	Default	Modification
PA-00	Acceleration time 1	0.0~3600.0s	20.0s	○
PA-01	Deceleration time 1	0.0~3600.0s	20.0s	○
PA-02	Acceleration time 2	0.0~3600.0s	20.0s	○
PA-03	Deceleration time 2	0.0~3600.0s	20.0s	○
PA-04	Acceleration time 3	0.0~3600.0s	20.0s	○

PA-05	Deceleration time 3	0.0~3600.0s	20.0s	○
PA-06	Jog acceleration time	0.0~3600.0s	20.0s	○
PA-07	Jog deceleration time	0.0~3600.0s	20.0s	○
PA-08	Hopping frequency1	0.0 ~ Upper limiting frequency (P0-09)	0.0Hz	○
PA-09	Hopping frequency2	0.0 ~ Upper limiting frequency (P0-09)	0.0Hz	○
PA-10	Amplitude of Hopping frequency	0.0 ~ Upper limiting frequency (P0-09)	0.0Hz	○
PA-11	FDT level value	0.0 ~ Upper limiting frequency (P0-09)	0.0Hz	○
PA-12	FDT lagged value	0.0~FDT level value (PA-11)	0.0Hz	○
PA-13	Amplitude of detected frequency FAR	0.0 ~ Upper limiting frequency (P0-09)	0.0Hz	○
PA-14	Setting count value	1~65535	1000	○
PA-15	Specified count value	1~65535	1000	○
PA-16	Underclocking function for overload	0: Disabled 1: Enabled	1	●

(PA-17~ PA-26 Reserved)

“○”: it indicates that it's only when converter is running or shut down on the condition that P0-00 equals zero that code parameters can be changed or modified.

“●”: it indicates that code parameters cannot be changed or modified while converter is running.

“×”: it indicates that code parameters are read-only, which cannot be changed or modified.

6-2 Detailed of function parameters(Explanations of Functional Parameters)

P0 Basic functional parameters

P0-00	Parameter setting mode	0: Enabled (except those parameters marked with"×") 1: Disabled (except P0-00) 99: Factory reset	Default: 0
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It's mainly applied to the setting of functional parameters; "factory reset" option should be used with caution, especially after all these parameters are set.

P0-01	Frequency setting mode	0: Frequency setting (UP/DOWN) 1: Panel potentiometer 2: External AI1 3: External AI2 4: PI regulation 5: UP/DOWN by the P5-20 add and subtract 6: UP/DOWN by the P5-20 add and subtract, frequency qing zero downtime	Default: 0
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It's mainly used to select the source of operating frequency for converter.

0: Frequency setting

The frequency of converter can be preset by parameter P0-03; frequency can be preset or changed directly through these two keys   on the panel when state information is displayed; it also can be changed directly by external terminals UP/DOWN when they are enabled.

1: Panel potentiometer

Operating frequency can be set by the potentiometer on the panel.

2 / 3: Preset of external analog voltage AI1 /AI2

Operating frequency not only can be set by the signal of external analog voltage(0.0~10.0V) sent out by AI1 or AI2 whose input voltage is formed by the synergy of internal +10V power source and potentiometer.

AI2 can be done through the signal of external analog current(0~20mA) via J4 jumper.

4: PI regulation

Precaution: Corresponding multispeed frequency will be applied firstly when external multispeed terminals are enabled. **For detailed information, please refer to the standard wiring diagram on Chapter 3.**

5, 6: frequency by external terminals given (note: each time the increase or decrease of a given frequency range be determined by the P5-20), when set to 6, the frequency converter after every stop, zero frequency

P0-02	Control mode for running	0: Controlled by keyboard 1: Controlled by terminals, STOP Key disabled 2: Controlled by terminals, STOP Key enabled	Default: 0
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It's mainly applied to the instruction sources of booting, stopping or jog for converter.

0: Converter can be controlled through the following three keys



which stand for booting, stopping, jog or forward/reverse accordingly.

1:  key will be disabled when converter is controlled by external terminals, including its booting, stopping, jog or forward/reverse running.

2:  key will be enabled when converter is controlled by external terminals, including its booting, stopping, jog or forward/reverse running.

P0-03	Frequency setting	0.0 Hz ~ Upper limiting frequency (P0-09)	Default: 50.0Hz
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Frequency of output can be set by setting this parameter only when P0-01 equals zero.

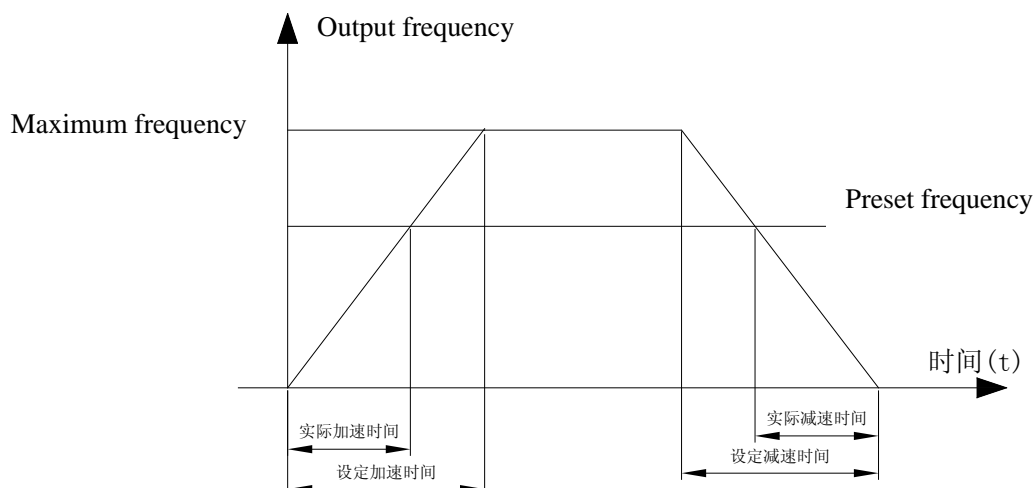
P0-04	Acceleration time 0	0.1s~3600.0s	Default: 20.0s
P0-05	Deceleration time 0	0.1s~3600.0s	Default: 20.0s



Acceleration time 0: Time for converter to increase its frequency from 0Hz to maximum frequency(P0-08).

Deceleration time 0: Time for converter to decrease its frequency from maximum frequency(P0-08) to 0Hz.

Please refer to following graph.:



Time

Actual acceleration time


Actual deceleration time

Preset acceleration time

Preset deceleration time

P0-06	Running direction	0: Default direction 1: Reverse direction	Default: 0
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Running direction can be preset through this parameter, which will also be taken as forward direction by default. It will also be chosen as a reference for reverse direction which is controlled by  key as well as external terminals.

0: Converter will be running in default direction

1: Running direction will be changed, which also means that it is changed by altering any two of motor wires(U, V, W).

P0-07	Anti-reversion Setting	0: Enabled 1: Disabled	Default: 0
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Running direction will be controlled by parameter "P0-06" when reverse direction is disabled. Both  key and external terminals will be disabled.

P0-08	Maximum frequency	Upper limit frequency (P0-09) ~400.0Hz	Default: 60.0Hz
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The setting of Acc-Dec time is based on maximum output frequency of running.

P0-09	Upper limiting frequency	Lower limiting frequency (P0-10) ~Maximum frequency (P0-08)	Default: 50.0Hz
P0-10	Lower limiting frequency	0.0Hz~Upper limiting frequency (P0-09)	Default: 0.0Hz



It's mainly applied to the setting of the amplitude between upper limiting

frequency and lower limiting frequency, which are also the range values of frequency regulation displayed on the panel potentiometer.

These two parameters are also related to the amplitude of upper limiting voltage and lower limiting voltage set by AI1 or AI2. For detailed information, please refer to P5-00~08.

P0-11	Jog frequency	0.0Hz~Upper limiting frequency (P0-09)	Default:5.0Hz
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It's mainly applied to the setting of running frequency for jog.

P0-12	Carrier frequency	1~16KHz	Default: Depending on model
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The switching frequency of interior power module is controlled by this parameter.

Audio noise and heat effect generated during the process of running are mainly affected by carrier frequency. Carrier frequency must be increased slightly in order to achieve a quieter running; however, the maximum load will be decreased somehow at the same time, which may increase the risk of electric leakage between motor lines or between wires and earth. When ambient temperature is too high or there is too much load for motor, carrier frequency should be decreased properly to improve converter's thermal characteristics.

Generally, carrier frequency will be preset right before delivery; therefore, it doesn't need to be reset or modified.

It should be used by derating if the carrier frequency which is being applied by operator exceeds the default value preset by factory.

P0-13	Carrier frequency Regulation	0: Regular PWM mode 1: Random PWM mode	Default: 0
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Noise frequency of motor is fixed while running in regular PWM mode; frequency domain of noise is wider while the running of motor is set in random PWM mode.

P0-14	Keyboard	0: Automatic storage when it powers	Default: 0
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	frequency (UP/DOWN)	down 1: No storage when it powers down	
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It's mainly used to alter the operating frequency through   keys or external terminals UP/DOWN. Whether a modified operating frequency would be saved in the parameter P0-03 after it powers down depends on the setting of this parameter.

P1: Human Interface parameters

P1-00	Default display information for Starting	0: Setting frequency 1: Output frequency 2: Output current 3: Bus voltage 4: Rotational Speed of motor 5: Percentage of output current 6: IGBT temperature 7: Output voltage 8: Output power 9: Count value 10: PI index value 11: PI feedback value 12: Accumulated running time (hour) 13: Input terminal status 14: Output terminal status 15: Power	Default: 0
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It's mainly applied to the setting of default display information for starting.

Set value	Status information	Descriptions	Unit
0	F 20.0	Preset frequency	Hz
1	H 0.0	Output frequency	Hz
2	C 0.0	Output current	A
3	U 540	Bus voltage	V
4	n 0	Rotational speed of motor	r/min
5	C. 0.0	Percentage of output current	
6	° 25	IGBT Temperature	°C
7	d 0	Output voltage	V
8	P 0.0	Output power	KW
9	A 0	Count value	
10	c 1.2	PI preset value	
11	3 1.1	PI feedback value	
12	r 0	Total run time	H
13		Status of input terminal	
14		Status of output terminal	
15	y 15.0	Converter power	KW


P1-01

Setting of


0: 0~3 messages

Default: 1



	display information	1: 0~7 messages 2: 0~11 messages 3: 0~15 messages	
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 It's mainly applied to the setting for how many messages are allowed to displayed on the panel. About the corresponding information for No. 0~15, please refer to P1-00.

1-02	Display coefficient of mechanical speed	0.1~60.0	Default: 29.0
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 It's mainly applied to the adjustment of displayed value for the rotational speed of motor. Display coefficient of mechanical speed = rotational speed of motor/operating frequency

P1-03	JOG/REV Function selection	0: Jog 1: FDW/REV switching	Default: 0
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 It's mainly applied to the features setup of  key; and when running is under the control of keyboard:

0: Jogging will be enabled by pressing  key;

1: Forward direction and reverse direction can be switched to each other by  key.

P2: Parameters of Start-Stop Mode

P2-00	Starting Mode	0: Starting directly 1: DC braking-Starting 2: Speed tracking after startup 3: Adaptive direction of speed tracking	Default: 0
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 **0:** It starts directly with the original start frequency;

1: DC braking-Starting -- DC braking will be enabled first; then motor starts running with the original start frequency; this is applicable for the situation when reverse may be caused by small inertia load during the process of starting.

2: the speed tracking after startup. Frequency converter for motor speed, but the motor according to the last stop in the direction of

the direction to run by default. (11 kw models more effective)

3: adaptive direction of speed tracking. Before starting the inverter in the automatic detection the direction of the electric motor no impact on the smooth startup of rotation of the motor. (11 kw models more effective)

P2-01	Starting frequency	0.0~10.0Hz	Default: 0.5 Hz
P2-02	Retention time for starting	0.0~50.0 s	Default: 0.0s



Applicable starting frequency can ensure that there is enough torque for starting.

Retention time for starting is needed for the formation of magnetic flow while motor is on standby, so that it can start accelerating after start frequency is stabilized for a certain time.

P2-03	Braking current before starting	0~150.0%	Default: 50.0%
P2-04	Braking time before starting	0~50.0s	Default: 0.0s



It's only when P2-00 equals 1 that DC braking can be enabled before starting. When converter is about to be started, DC braking should be proceeded according to the preset braking current (P2-03); after the preset braking time (P2-04) is over, it will start running.



Braking current means the percentage comparing with rated current. The higher braking DC is, the stronger braking force will be.

P2-05	Stop mode	0: Regular stopping 1: Stop by decelerating 2: Decelerating - DC braking - Stopping	Default: 1
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It's mainly applied to the setting of stop mode for converter.

0: Regular stopping -- the output of converter will be blocked immediately once stop instruction comes into effect.

1: Stopping by decelerating -- output frequency will be decreased slowly according to

the preset deceleration time once stop instruction comes into effect; when it comes to zero, converter will be shut down.

2: Decelerating - DC braking - Stopping: output frequency will be reduced down to start frequency(P2-06) according to the preset deceleration time once stop instruction comes into effect; since then, DC braking will be enabled; after braking time(P2-08) is over, converter will be shut down.

P2-06	Start frequency of DC braking	0.0~10.0Hz	Default: 0.0Hz
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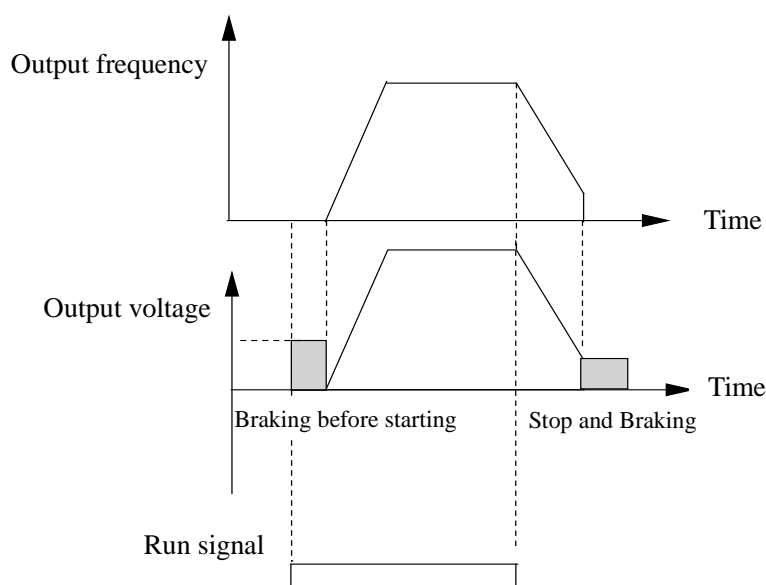
If parameter P2-05 equals two, it will be stopped through DC braking when converter reaches up to the corresponding frequency.

P2-07	Braking current for stopping	0~150.0%	Default: 50.0%
P2-08	Braking time for stopping	0~50.0s	Default: 0.0s



Braking current for stopping means the amperage of direct current for braking; the higher the amperage is, the stronger the braking force will be.

Braking time for stopping means the time for increasing enough amperage of direct current to stop converter; when the value comes to zero, it means that there is no DC braking during the process.

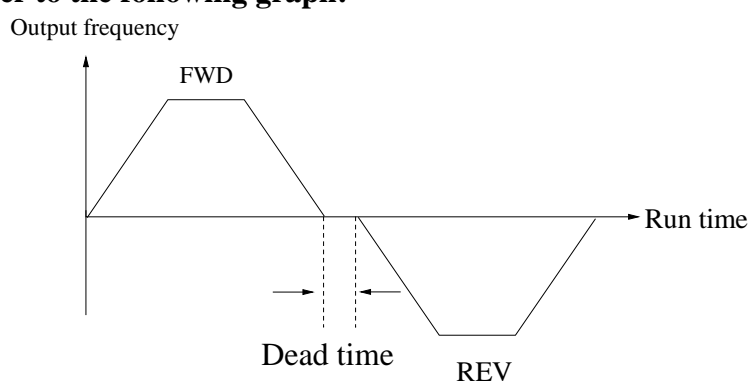


P2-09	Dead time of FWD/REV	0.0~50.0 s	Default: 0.0s
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It mainly applied to the setting of transient time for zero output frequency during the transient process between forward and reverse.

Please refer to the following graph:



P2-10	Lower limiting frequency for running control	0: running in lower limiting frequency 1: on standby 2: stopping	Default: 0
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It's mainly applied to the setting of running status when preset frequency is less than lower limiting frequency.

0: Converter will be running in lower limiting frequency if preset frequency is less than lower limiting frequency.

1: Converter will be shut down when preset frequency is less than lower limiting frequency; and it will be started again automatically when preset frequency is higher than or equivalent to lower limiting frequency.

2: This parameter is applicable to stop the converter in case that motor keeps running in a low speed.

P3: Parameters of Motor

P3-00	Rated frequency	F3 (P4-05) ~400Hz	Default: 50.0Hz
P3-01	Rated voltage	200~440V	Default: Depending on model
P3-02	Rated current	0.1~999.9A	Default: Depending on model
P3-03	Rated power	0.1~630.0KW	Default: Depending on model
P3-04	Rated rotational Speed	1~36000rpm	Default: 1440rpm



These parameters above must be set according to the information of nameplates on the motor.

These parameters of motor must be accurate in order to improve the performance of self-adaptive control. These parameters of typical four-pole motor which is compatible with this converter by default are included, which should be input when the capacity of motor is not in conformity with that of this converter.

P3-05	No-load current	0.1~999.9A	Default: Depending on model
P3-06	Stator resistance	0.001~50.000Ω	Default: Depending on model
P3-07	Excitation/Magnetic inductance	0.1~5000.0mH	Default: Depending on model



These parameters above are mainly applied to the setting of basic electrical parameters, which are essential to complete the algorithm of self-adaptive control.

If the capacity of the matched motor is also the same as that of typical motor, the default parameters can be applicable.

They can also be input manually if those precise parameters can be obtained in advance. All the internal default parameters will be restored automatically according to its model during the process of initialization.

Precaution: Do not change or modify these parameters casually.

P4: V/F Control Parameters

P4-00	V/F curve setting	0: General V/F 1: 2 power V/F 2: 3 power V/F 3: high starting torque V/F 4: Self-setting V/F 5: Self-adaptive control	Default: 0
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It's mainly applied to the setting of corresponding curves for output voltage and output frequency according to different conditions of loading.

0: General V/F is generally applicable to constant load torque;

1/2: 2 or 3 power V/F is applicable to the operation with centrifugal load, for example draught fan or pump, etc.

3: high starting torque V/F is applicable to the operating situations which require higher starting torque.

4: Self-setting V/F indicates that V/F curve can be preset randomly by the functional codes P4-01~P4-06, which is applicable to the operation with special load, for example dewaterer or centrifuge, etc.

5: Self-adaptive control can be applied to running regulation by adapting itself to actual load automatically, which is applicable to the operating situations which require greater low-frequency torque as well as strict control on speed.

Parameters must be set correctly according to the information of nameplate on the motor if this function needs to be enabled; it's only when the capacity of the motor is the same as that of this converter can its performance be improved greatly.

P4-01	V/F Intermediate	0.0Hz~P4-03 (Intermediate frequency 2)	Default: 5.0Hz
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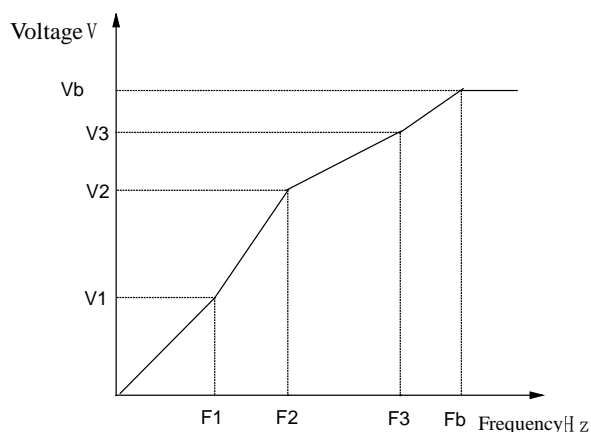
	frequency 1		
P4-02	V/F Intermediate voltage1	0~ rated voltage (P3-01)	Default: 38V
P4-03	V/F Intermediate frequency 2	P4-01(Intermediate frequency 1)~P4-05 (Intermediate frequency)	Default: 25.0Hz
P4-04	V/F Intermediate voltage 2	0~ rated voltage (P3-01)	Default: 190V
P4-05	V/F Intermediate frequency 3	P4-03 (Intermediate frequency 2) ~ P3-00(rated frequency)	Default: 50.0Hz
P4-06	V/F Intermediate voltage 3	0~ rated voltage (P3-01)	Default: 380V



Multiple-phase V/F curves can be defined by these six parameters above (P4-01~P4-06)

The set value of V/F curves is generally set according to the load characteristics of motor.

Precaution: motor may be overheated or even burned if preset low-frequency voltage is too high, which may activate its over current protection. $V1 < V2 < V3$, $F1 < F2 < F3$.



P4-07	Torque upgrade	0.0~15.0%	Default: 0
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This parameter can make compensation for output voltage when converter is running in a low frequency, so that the characteristics of low-frequency torque which

is controlled by V/F can be compensated and upgraded.

If the setting of torque upgrade is too high, not only motor tends to be overheated but also over current may be caused by it. In general, the setting of torque upgrade must be no more than 10%. To prevent converter from over current effectively, this parameter must be adjusted properly. This parameter should be increased whenever there is heavy load; otherwise, please decrease this parameter.

P4-08	Slip compensation	0.0~10.0Hz	Default: 0.0 Hz
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The practical slip of motor varies from load to load. Output frequency can be adjusted automatically according to the condition of loading by this functional parameter, so that compensation can be made for the influence of load on rotational speed of motor.

P4-09	AVR function	0: Disabled 1: always enabled 2: only enabled in process of deceleration	Default: 1
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AVR function is also known as Automatic Voltage Regulation function. Adjustment will be made automatically to stabilize output voltage whenever there is fluctuation of input voltage, so that it can prevent converter from overheat of motor caused by high output voltage or poor performance caused by low output voltage.

Effective period of AVR can be selected by this parameter. AVR option will be disabled when converter is stopped by decelerating; though the deceleration time is very short, the current is a little high. When AVR option is enabled, the deceleration time will be longer, but the current will be lower.

P4-10	Energy-efficient running	0: Disabled 1: Enabled	Default: 0
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During the process of no-load or light-load running, output voltage can be adjusted properly to achieve automatic energy conservation by detecting load current.

This parameter is applicable to the load of draught fan or pump.

P5: Input function parameters

P5-00	AI1 lower limiting value	0~10.00V	Default: 0.00V
P5-01	Corresponding setting for AI1 lower limit	0~100.0%	Default: 0.0%
P5-02	AI1 upper limiting value	AI1 lower limiting value~10.00V	Default: 10.00V
P5-03	Corresponding setting for AI1 upper limit	0~100.0%	Default: 100.0%
P5-04	AI1 input filtering time	0.0s~10.0s	Default: 0.1s

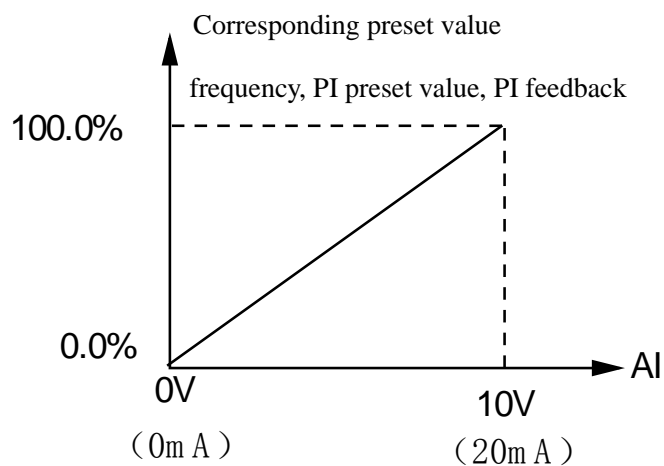


The functional codes above define the relationships between analogue input voltage and corresponding setting of AI. Calculation will be based on the maximum or minimum one whenever analogue input voltage exceeds the range between preset maximum input and minimum input.

The corresponding nominal value of analogue setting varies from situation to situation. For detailed information, please refer to the relevant instructions for each parameter.

The following graphs are listed to demonstrate several situations of setting.

Precaution: preset lower limiting value of AI1 must be less than or equivalent to preset upper limiting value of AI1.



The sensitivity of analogue input is decided by AI1 input filtering time. The parameter must be increased to improve the anti-jamming capability which can prevent analog quantity from being interfered, so that malfunctions can be reduced somehow; however, it may reduce the sensitivity of analogue input.

P5-05	AI2 lower limiting value	0.00V~10.00V	Default: 0.00V
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P5-06	Corresponding setting for AI2 lower limit	0~100.0%	Default: 0.0%
P5-07	AI2 upper limiting value	AI2 lower limiting value~10.00V	Default: 10.00V
P5-08	Corresponding setting for AI2 upper limit	0~100.0%	Default: 100.0%
P5-09	AI2 input filtering time	0.0s~10.0s	Default: 0.1s



The setting of AI2 function is similar to that of AI1. 0~20mA input current is equivalent to 0~10V input voltage when analogue input is preset as current input. 0~10V or 0~20mA input can also be selected through jumper 4(J4).

P5-10	Multi-functional Input Terminal X1	0: Disabled	Default: 1
P5-11	Multi-functional Input Terminal X2	1: Forward 2: Reverse 3: Three-wire control 4: Multi-phase reference velocity 1	Default: 2
P5-12	Multi-functional Input Terminal X3	5: Multi- phase reference velocity 2 6: Multi- phase reference velocity 3	Default: 14
P5-13	Multi-functional Input Terminal X4	7: JOG forward 8: JOG reverse	Default: 4
P5-14	Multi-functional Input Terminal X5 (CN1 needle base input)	9: Increasing frequency 10: Decreasing frequency 11: Acc-Dec time selection 1 12: Acc-Dec time selection 2	Default: 5
P5-15	Multi-functional Input Terminal X6	13: Acc-Dec pause 14: External fault Input 15: Fault reset	Reserved
P5-16	Multi-functional Input Terminal X7	16: Freely stopping 17: External count value input 18: count clear	Reserved
P5-17	Multi-functional Input Terminal X8	19: program run 20: pause of program run	Reserved



It's mainly applied to the setting of corresponding functions for digital mutil-functional input terminals.

Set value	Functions	Descriptions																																													
0	Disabled	Please set unused terminals to be invalid to avoid malfunction. It's applied to the setting of terminals which have no function; those additional terminals can be set as non-functional terminals to prevent converter from malfunctioning																																													
1	Forward	Set the forward and reverse of converter. Please refer to description of P5-18 It's applied to the setting of terminals which control the running direction(forward/reverse) of converter; for detailed information, please refer to the instruction on Page5~18																																													
2	Reverse																																														
3	3-wire control	Please refer to description of P5-18 It's applied to the setting of three-wire control terminals(it's activated only when three-wire control is enabled); for detailed information, please refer to the instruction on Page5~18																																													
4	Multi-phase reference velocity 1	<div>8 steps speed control can be realized by the combination of these four terminals. Eight kinds of speeds can be set through the combination of numbers which are decided by three terminals separately</div> <table><tr><th>S₃</th><th>S₂</th><th>S₁</th><th>Frequency</th><th>Parameter</th></tr><tr><td>0</td><td>0</td><td>0</td><td>Multi-phase reference velocity 0</td><td>P0-03</td></tr><tr><td>0</td><td>0</td><td>1</td><td>Multi-phase reference velocity 1</td><td>P8-01</td></tr><tr><td>0</td><td>1</td><td>0</td><td>Multi-phase reference velocity 2</td><td>P8-02</td></tr><tr><td>0</td><td>1</td><td>1</td><td>Multi-phase reference velocity 3</td><td>P8-03</td></tr><tr><td>1</td><td>0</td><td>0</td><td>Multi-phase reference velocity 4</td><td>P8-04</td></tr><tr><td>1</td><td>0</td><td>1</td><td>Multi-phase reference velocity 5</td><td>P8-05</td></tr><tr><td>1</td><td>1</td><td>0</td><td>Multi-phase reference velocity 6</td><td>P8-06</td></tr><tr><td>1</td><td>1</td><td>1</td><td>Multi-phase reference velocity 7</td><td>P8-07</td></tr></table>	S ₃	S ₂	S ₁	Frequency	Parameter	0	0	0	Multi-phase reference velocity 0	P0-03	0	0	1	Multi-phase reference velocity 1	P8-01	0	1	0	Multi-phase reference velocity 2	P8-02	0	1	1	Multi-phase reference velocity 3	P8-03	1	0	0	Multi-phase reference velocity 4	P8-04	1	0	1	Multi-phase reference velocity 5	P8-05	1	1	0	Multi-phase reference velocity 6	P8-06	1	1	1	Multi-phase reference velocity 7	P8-07
S ₃	S ₂		S ₁	Frequency	Parameter																																										
0	0		0	Multi-phase reference velocity 0	P0-03																																										
0	0		1	Multi-phase reference velocity 1	P8-01																																										
0	1		0	Multi-phase reference velocity 2	P8-02																																										
0	1		1	Multi-phase reference velocity 3	P8-03																																										
1	0		0	Multi-phase reference velocity 4	P8-04																																										
1	0		1	Multi-phase reference velocity 5	P8-05																																										
1	1		0	Multi-phase reference velocity 6	P8-06																																										
1	1		1	Multi-phase reference velocity 7	P8-07																																										
5	Multi-phase reference velocity 2																																														
6	Multi-phase reference velocity 3																																														
7	Forward jogging	Set the jog forward and jog reverse of converter It's applied to the setting of terminals which control jogging direction(forward/reverse)																																													
8	Reverse jogging																																														
9	Increasing frequency(Up)	The reference frequency of inverter can be adjusted by UP command and DOWN command. It's applied to the setting of external terminals which can change or																																													

10	Decreasing Increasing (Down)	modify the instructions to increase or decrease frequency. Upward or downward adjustment of frequency can be made through these two functions when frequency is set decided by number.			
11	Acc-Dec time Option 1	4 groups of ACC/DEC time can be selected by the combination of these two terminals. Four kinds of Acc-Dec times can be set through the combination of numbers which are decided by two terminals separately			
12	Acc-Dec time Option 2	Terminal 2	Terminal 1	Acc-Dec time Options	Parameter
		0	0	Acc-Dec time 0	P0-04、 P0-05
		1	1	Acc-Dec time 1	PA-00、 PA-01
		1	0	Acc-Dec time 2	PA-02、 PA-03
		1	1	Acc-Dec time 3	PA-04、 PA-05
13	Stop of Acc/Dec	When the terminal is valid, in ACC/DEC situation, it is running as current frequency. Acceleration or deceleration mode will be shut down when terminals are enabled; converter will be running in current frequency.			
14	External fault Input	Stop the inverter and output a alarm when a fault occurs in a peripheral device Converter can detect fault and shut itself down automatically when external fault signal is received.			
15	Fault reset	Resets faults that have occurred. It has the same function a RESET key It functions as RESET key functions, which can also be used to achieve remote control of fault reset.			
16	Regular stopping	The inverter blocks the output immediately. The motor coasts to stop by its mechanical inertia. The process of stopping will not be affected by converter if there is no output signal sent to motor. It's applicable to any situation and the operation with large inertia load.			
17	External count value input	Outer count input/pulse input Switching value of external count / pulse input			
18	Counter reset	To counter the state cleared To reset the counter			
19	Program run	program is running according the terminal Program can be started by the terminal			

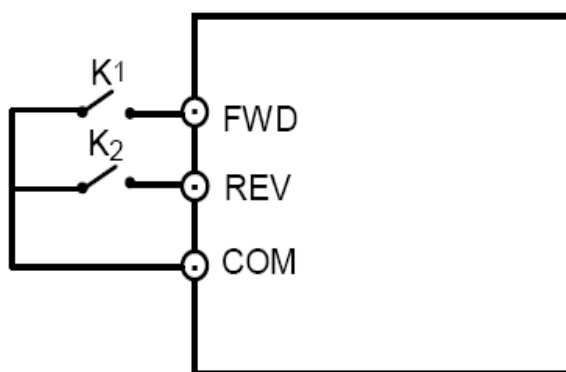
20	Pause of program run	Keep the converter in current running frequency when the terminal is valid, and the running time is not include in program running time It can keep converter running in current frequency when terminals are enabled; during this period, running time is not count into the time of program run
20~31	Reserved	Reserved

P5-18	Terminal control mode	0: Two-wire control mode 1 1: Two-wire control mode 2 2: Three-wire control mode 1 3: Three-wire control mode 2	Default: 0
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This parameter defines three different control modes of external terminals.

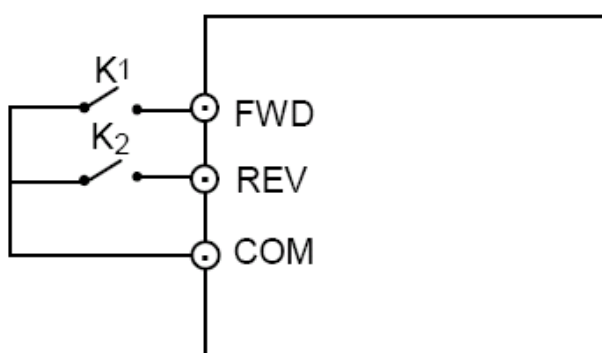
0: Two-wire control mode 1 is the most common two-wire mode, which can make directions conformed with each other; Forward or reverse direction will be decided by the instructions from FWD/REV terminals.



K1	K2	Command code
OFF	OFF	Stop
ON	OFF	Forward
OFF	ON	Reverse

●2-wire control mode 1

1: Two-wire control mode 2 can keep directions separated with each other; FWD terminal will be enabled while this mode is enabled; but direction will be decided by REV.

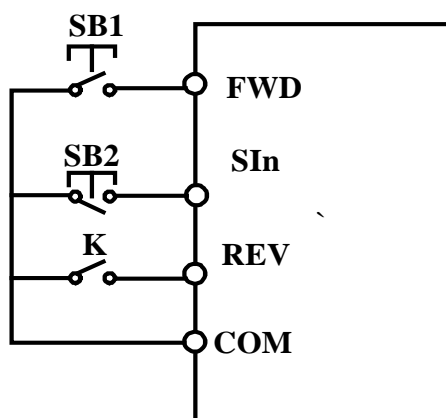


K1	K2	Run command
OFF	OFF	Stop

OFF	ON	Stop
ON	OFF	Forward
ON	ON	Reverse

2-wire control mode 2

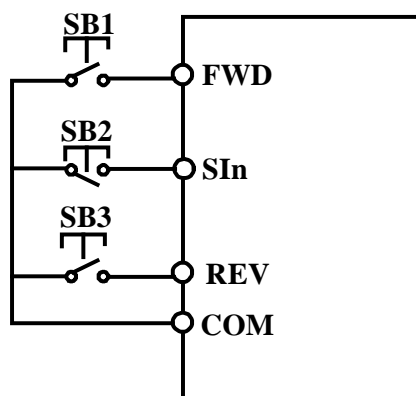
2: Rising edge of pulse and terminal SIn will be enabled while three-wire control mode 1 is enabled; direction is controlled by REV key; stop signal is controlled by input terminal SIn. The function of corresponding input terminal is defined by SIn terminal as No.3 function "three-wire control".



K	OFF	Forward
	ON	Reverse
SB1	Run	
SB2	Stop	

3-wire control mode 1

3: Rising edge of pulse and terminal SIn will be enabled while three-wire control mode 2 is enabled; run command is controlled by both REV of FWD keys which control the running direction at the same time; stop signal is generated by a constant-closed input terminal SIn. The function of corresponding input terminal is defined by SIn terminal as No.3 function "three-wire control".



SB1	Forward running
SB2	Stop
SB3	Reverse running

3-wire control mode 2

Tips: As for two-wire control mode, with the premise of the following two points, even control terminals FWD/REV remain enabled, converter will not be running any more after stop signal disappears:

- 1) FWD/REV terminals are enabled;
 - 2) Converter is shut down because of stop signal generated by the other source;
- FWD/REV terminals must be enabled again if converter needs to be started.

P5-19	Terminal filtering time	2ms~100 ms	Default: 10 ms
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It's mainly used to set the sensitivity of terminals from X1 to X8. The parameter must be increased to improve the anti-jamming capability which can prevent DI terminals from being interfered, so that malfunctions can be reduced somehow; however, it may reduce the sensitivity of DI terminals.

P5-20	The range of the UP/DOWN increasing decline	0.0~50.0Hz	0.1
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When frequency increment/decrement with external terminal set, every time the frequency of the increase or decrease in value is decided by the P5-20.

P6: Output function parameters

P6-00	Y1 output options	0: Disabled	Default: 1
		1: Running	Default: 2

P6-01	Y2 output options	2: Direction	Default: 3
	Relay output options	3: Fault output 4: On standby 5: Frequency received 6: FDT 7: Upper limiting frequency received 8: Lower limiting frequency received 9: Setting count value received 10: Designated count value received	

**Table of Output Functions**

Set value	Functions	Descriptions
0	Disabled	Output terminals without any function
1	Running	When the converter is running, output the close signal It means that converter is running; closed signal is output.
2	Direction	On run reverse, output the close signal It indicates the running direction of converter; closed signal is output when it's running in reverse direction.
3	Fault output	When the converter is out of work, output the close signal Closed signal is output when it's malfunctioning.
4	On standby	Establish main circuit and control circuit power, the protection function of the converter is not change, and the converter is running, output the close signal Major loop and control circuit are established; protection function isn't enabled; converter is on standby; closed signal is output.
5	Frequency received	Please refer to the explanations of function code PA-11~13
6	FDT	
7	Upper limiting frequency received	ON: Running frequency reaches the value of P0-09 Signal "ON" is output when running frequency reaches upper limiting frequency
8	Lower frequency limiting received	ON: Running frequency reaches the value of P0-10 Signal "ON" is output when running frequency is equivalent to or lower than lower limiting frequency

9	Setting count value received	ON: the value of count reach the setting value of PA-14 Signal "ON" is output when count value reaches the value set by PA-14.
10	Designated count value received	ON: the value of count reach the setting value of PA-15 Signal "ON" is output when count value reaches the value set by PA-15.
11~15	Reserved	Reserved

P6-03	AO1 options	0: Operating frequency 1: Output current 2: Bus voltage 3: Output voltage	Default: 0
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The standard range of analogue input current/voltage is 0~20mA/0~10V, which can be selected by Jumper 5. Output signals can be selected by the setting of this parameter, which correspond to output frequency or output current of converter.

Corresponding range of AO(0~10V/0~20mA) is as followed:

Set value	Functions	Descriptions
0	Running frequency	0~upper limiting frequency
1	Output current	0~double rated current
2	Bus voltage	0~ double rated voltage
3	Output voltage	0~ double rated voltage

P6-04	AO correction coefficient	0.0~250.0%	Default: 100.0%
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It's mainly not only applied to the correction of analogue output voltage but also used to adjust the range of analogue output voltage.

Analogue output voltage = Analogue output voltage × AO correction coefficient

If the set value of parameter P6-03 is zero while the set value of parameter P6-04 is 100%, the corresponding AO of upper limiting frequency is +10V (20mA). AO correction coefficient can be increased properly to calibrate the analogue output voltage if practical AO is only 9.8V because of differences of circuit.

P6-05	Stop delay time setting	0~3000.0S	0
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When the inverter output signal when stop the machine open, until the P6-05, the output signal to shut down.

P7: PI control parameters

PI control is a common method to control the process. Output frequency can be adjusted by proportion & integral operations on the difference between the feedback signals of controlled variable and signals of objective variables.

P7-00	PI preset source options	0: Digital keyboard 1: Panel potentiometer 2: Analog channel AI1 3: Analog channel AI2	Default: 0
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This parameter functions if PI is chosen as frequency source, which means that the selection of P0-01 is option 4. The preset channel of objective variables for PI is determined by this parameter. The setting **objective variables of PI are relative value; the percentage of the setting(100%) corresponds to the percentage of feedback signal(100%) in the controlled system. And operation is proceeded by the system according to the relative value(0~100%).**

P7-01	PI set value	0.00~10.00V	Default: 0.00
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When P7-00 equals zero, PI set value will be set by this parameter.

P7-02	PI feedback source options	0: Analog channel AI1 1: Analog channel AI2	Default: 0
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PI feedback channel is determined by this parameter.

P7-03	PI output characteristics options	0: Positive 1: Negative	Default: 0
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Positive PI output characteristics: output frequency must be lowered to make it balance when the value of feedback signal is greater than PI set value, for example PI control on winding tension.

Negative PI output characteristics: output frequency must be increased to make it

balance when the value of feedback signal is greater than PI set value, for example PI control on unwinding tension.

P7-04	Proportional gain (P)	0.0~10.0	Default: 0.1
P7-05	Integral time (I)	0.0~100.0s	Default: 0.1s

Proportional gain (P) determines the intensity of adjustment of PI regulator; the larger P value is, the higher the intensity of adjustment will be.

Integral time (I) determines the speed of integral regulation on the difference between PI feedback quantity and given quantity. The less integral time is, the higher the intensity of adjustment will be.

PI is the most common control method for process control; the function of each part is different from each other's. Please refer to the following brief introduction of operating principles and regulation methods:

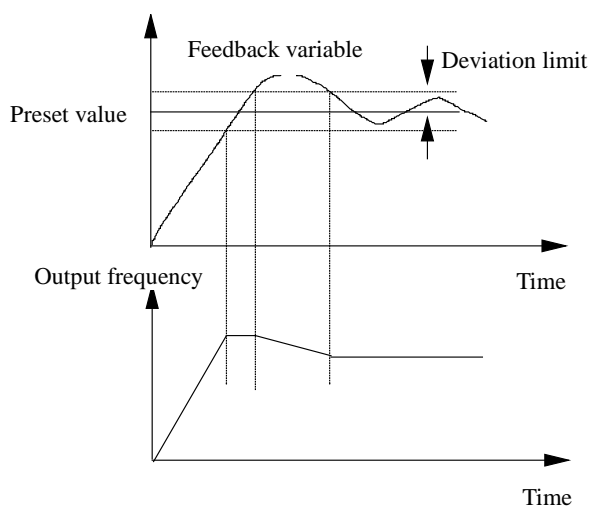
Proportional gain (P): There will be proportional adjustment between output and deviation if there is difference between feedback value and set value; if deviation is constant, regulating variable is also constant. Proportional control responses to the change of feedback quickly; however, error control can't be proceeded only by proportional control. The greater proportional gain is, the smaller adjusting speed of system will be. But the proportional gain is excessive, it may cause vibration. The adjustment method is to extend the integral time and make system running only by proportional control; meanwhile, set value should be changed in order to observe its stable deviation(static error) between feedback signal and given quantity; if static error is in compatible with the change of given quantity, proportional gain can be increased continuously, for example increasing given quantity, or feedback quantity is always less than given quantity after system is stable; otherwise, please reduce it. The instruction above should be implemented repeatedly until deviation is optimized/minimized(tips: zero offset is almost impossible).

Integral time (I): when there is difference between feedback value and set value, regulating variable of output should be accumulated continuously; if the deviation

can't be eliminated, the regulating variable should be increased continuously until there is no deviation. Deviation can be eliminated effectively by integral controller. However, overshoot may be caused repeatedly if the adjustment of integral controller is too much, which makes system unstable and even causes vibration. If vibration is caused by excessive integral action, following characteristics can be observed -- oscillation of feedback signal on given quantity, expanding amplitude of oscillation, even vibration. The parameter of integral time should be adjusted generally from maximum value to minimum value so that the integral time can be changed gradually. Observation should be made on the effect on the system. Adjustment can't be stopped until the stable speed of system meets the requirements.

P7-06	Deviation limit of PI control	0.00~2.00	Default: 0.10
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Deviation limit of PI control defines the comparison between PI system output and maximum deviation value which is limited by closed-loop set value. As is shown in the graph, PI regulator is shut down while it's within deviation limit. The precision and stability of PI system can be improved by setting this function code properly.



P7-07	Sampling period(T)	0.1~100.0s	Default: 0.5s
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Sampling period (T) means sampling period of feedback quantity; operation is

performed by regulator once every one sampling period. The longer sampling period is, the slower response will be.

P7-08	Detected value of feedback disconnection	0.00~5.00	Default: 0.10
P7-09	Time for detecting feedback disconnection	0.0~100.0s	Default: 1.0s

The feedback variable of PI can be always detected by system; if feedback variable is less than the detected value of feedback disconnection, system will consider feedback signal to be disconnected by default; if feedback variable is still less than the detected value of feedback disconnection while actual time is more than the time for detecting feedback disconnection, PIE can be detected and sent out by the system.

P7-12	Sleep time	0~3000S	600
P7-13	Dormancy pressure	0~10.00	0
P7-14	Dormancy frequency	0~50.0Hz	0
P7-15	Wake up the pressure	0~10.00	0



Dormancy function description: when the back pressure value > dormancy pressure (P7-13), the frequency of running < dormancy frequency (P7-14). Waiting for the time of sleep (P7-12), began to sleep. When the pressure of the feedback < wake up pressure (P7-15), will cease to dormancy, inverter will run again.

1.1 Dormancy frequency (P7-14) Settings:

In under the condition of no water or gas, make the inverter running in the PID control mode (P0-01 = 0 or 1), start the inverter. Observation line pressure, slowly increase the frequency to the target according to user's requirements, record the current operating frequency after downtime. Set the dormant frequency (P7-14) just above the record frequency of 1-3 hz or so.

1.2 dormancy pressure (P7-13) set: dormancy pressure value slightly smaller than the target value.

1.3 when a dormant frequency P7-14 = 0 or resting pressure P7-13 = 0, don't start the sleep function.

P8: Simple PLC and Multispeed Parameters

P8-00	Program run mode	0: Disabled 1: Program stop after one-cycle running 2: Program operates as last program runs after one-cycle running 3: Circulatory running of program	Default: 0
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0: Disabled

1: Program stop after one-cycle running

Converter will be stopped automatically after one-cycle running; only after run command is entered again will it be started.

2: Program operates as last program runs after one-cycle running

The operating frequency and direction in the last program will be remained to the end after one-cycle running.

3: Circulatory running of program

The next cycle of operation will be proceeded by converter automatically right after one-cycle running; system will not be shut down until stop command is received.

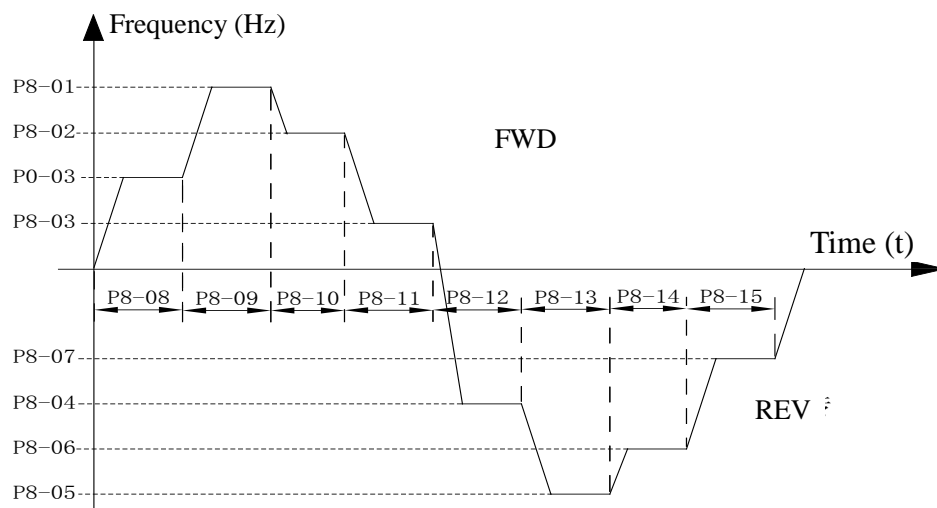
P8-01	First phase speed	Lower limiting frequency ~ Upper limiting frequency	Default: 0.0Hz
P8-02	Second phase speed	Lower limiting frequency ~ Upper limiting frequency	Default: 0.0Hz
P8-03	Third phase speed	Lower limiting frequency ~ Upper limiting frequency	Default: 0.0Hz
P8-04	Forth phase speed	Lower limiting frequency ~ Upper limiting frequency	Default: 0.0Hz
P8-05	Fifth phase speed	Lower limiting frequency ~ Upper limiting frequency	Default: 0.0Hz
P8-06	Sixth phase speed	Lower limiting frequency ~ Upper limiting frequency	Default: 0.0Hz
P8-07	Seventh phase	Lower limiting frequency ~ Upper limiting frequency	Default: 0.0Hz

	speed	frequency	
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These parameters above are mainly applied to the setting of seven different phase speeds; principal frequency is still controlled by parameter P0-03.

P8-08	Runtime of principal frequency	0~6400.0	Default: 0.0
P8-09	First phase time	0~6400.0	Default: 0.0
P8-10	Second phase time	0~6400.0	Default: 0.0
P8-11	Third phase time	0~6400.0	Default: 0.0
P8-12	Forth phase time	0~6400.0	Default: 0.0
P8-13	Fifth phase time	0~6400.0	Default: 0.0
P8-14	Sixth phase time	0~6400.0	Default: 0.0
P8-15	Seventh phase time	0~6400.0	Default: 0.0
P8-16	Time unit of multi-velocity	0: second 1: minute 2: hour	Default: 0

These parameters from P8-08 to P8-15 are mainly applied to the setting of run time for the velocity of each phase. Time unit can be preset by parameter P8-16.



P8-17	Running directions	0~255	Default: 0
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It's mainly applied to the setting of running directions for each program, which is preset by binary mode (8 bit). Parameter can be entered only after the binary value is converted into decimal value.

Weighted value	2^7	2^6	2^5	2^4	2^3	2^2	2^1	2^0
Binary set value	0	1	0	0	1	0	1	0
BIT	7	6	5	4	3	2	1	0

0: Forward
1: Reverse

- Running directions of Principal frequency: FWD
- Running directions of first phase: REV
- Running directions of second phase: FWD
- Running directions of third phase: RVE
- Running directions of forth phase: FWD
- Running directions of fifth phase: FWD
- Running directions of sixth phase: REV
- Running directions of seventh phase: FWD

Hence P8-17 should be set as 74

It's mainly applied to the setting of Acc/Dec time for each program, which is preset by binary mode (16 bit). Parameter can be entered only after the binary value is converted into decimal value.

Weighted value	2^{15}	2^{14}	2^{13}	2^{12}	2^{11}	2^{10}	2^9	2^8	2^7	2^6	2^5	2^4	2^3	2^2	2^1	2^0
Binary set value	0	0	0	0	0	0	0	0	1	1	1	0	0	1	0	0
BIT	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0

主频率加减速时间0
 第一段加减速时间1
 第二段加减速时间2
 第三段加减速时间3

Acc/Dec time 0 of Principal frequency
 Acc/Dec time 1 of first program
 Acc/Dec time 2 of second program
 Acc/Dec time 3 of third program
 Acc/Dec time 0 of forth program
 Acc/Dec time 0 of fifth program
 Acc/Dec time 0 of sixth program
 Acc/Dec time 0 of seventh program

Parameter values= (0000000011100100)₂ = (228)₁₀

Hence the P8-18 should be set as 228

P9: Protection Function parameters

P9-00	Options for overload protection	0: Disabled 1: Enabled	Default: 0
P9-01	Critical point of overload protection	50~120%	Default: 110%

These two parameters are mainly applied to the setting of real-time relay protection of load motor. Effective thermal protection of motor can be achieved by setting this parameter correctly when rated current of motor is not matched with rated current of converter.

Critical point of overload protection (motor) = (allowed max. load current / rated current of motor) * 100%

P9-02	Overvoltage protection	0: Disabled 1: Enabled	Default: 1
P9-03	Critical point of Overvoltage	110.0~150.0%	Default: 125

Due to the influence of inertia load, actual droop rate of motor's rotational speed may be lower than droop rate of output frequency while converter is decelerating; meanwhile, electrodes may feedback electric energy to converter, which may raise the bus voltage of converter. If no action is taken in time, stripping may be caused by overvoltage of busbar.

Overvoltage protection function will be enabled so that the decreasing output frequency of converter can be slowed down if bus voltage detected by converter while running exceeds the critical point of overvoltage defined by parameter P9-03(in comparison with standard bus voltage); if it's detected that the bus voltage is lower than the critical point, converter will continue to decelerate again.

P9-04	Over-current protection	0: Disabled 1: Enabled	Default: 1
P9-05	Critical point of over-current	100~180%	Default: 150

Because of excessive load, actual rate of rotational speed rise of motor may be lower than the rate of output frequency rise while converter is decelerating; if no action is taken in time, stripping may be caused by over current.

Over-current protection function will be enabled so that increasing output frequency of converter can be slowed down if bus current detected by converter while running exceeds the critical point of over current defined by parameter P9-05; if it's detected that output current is lower than the critical point, converter will continue to accelerate again.

P9-06	Phase-failure protection of input	0: Disabled 1: Enabled	Default: 0
P9-07	Phase-failure protection of output	0: Disabled 1: Enabled	Default: 0

Phase-failure protection of input: options are selected to enable or disable phase-failure protection for input

Phase-failure protection of output: options are selected to enable or disable phase-failure protection for output

P9-08	Latest fault information	0~20	
P9-09	Last fault information	0~20	
P9-10	Last two	0~20	

	fault messages		
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These parameters above can't be modified or changed; they are read-only.

The latest three fault types can be recorded by converter:

Zero means there is no malfunction

1~20 stands for twenty different malfunctions; for detailed information, please refer to Chapter 7 “Fault Correcting”.

P9-11	Operating frequency of latest fault		
P9-12	Output current of latest fault		
P9-13	Bus voltage of latest fault		
P9-14	Input state of latest fault		
P9-15	Output state of latest fault		

These parameters above can't be modified or changed; they are read-only.

Status information about the latest malfunctions can be recorded by converter, including its operating frequency, current and voltage.

P9-16	Fault since the reset function	0: invalid 1: under-voltage fault alarm automatic reset (unlimited) 2 ~ 20: fault self-recovery	0
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Please set this function carefully, to ensure that the fault occurs again after the operation of the safety of person or equipment.

After 2 ~ 20: frequency converter fault alarm automatically reset the number of times. Under-voltage alarm reset is always valid.

Parameters of PA Enhancements

PA-00	Acceleration time 1	0.0~3600.0s	Default: 20.0s
PA-01	Deceleration time 1	0.0~3600.0s	Default: 20.0s
PA-02	Acceleration time 2	0.0~3600.0s	Default: 20.0s
PA-03	Deceleration time 2	0.0~3600.0s	Default: 20.0s

PA-04	Acceleration time 3	0.0~3600.0s	Default: 20.0s
PA-05	Deceleration time 3	0.0~3600.0s	Default: 20.0s

Acc/Dec times are available to be selected, included three kinds of Acc/Dec times above, P0-04 and P0-05. They are all the same in definition; for detailed explanations, please refer to P0 series.

Acc/Dec time 0~3 can be selected through different combinations of multi-functional digital input terminals.

PA-06	Jog acceleration time	0.0~3600.0s	Default: 20.0s
PA-07	Jog deceleration time	0.0~3600.0s	Default: 20.0s

These two parameters above are applied to the definition of Acc/Dec time for jogging which can be started or stopped through direct starting or stop by decelerating.

Jog acceleration time indicates the time for converter to accelerate from 0 Hz to maximum frequency (P0-08).

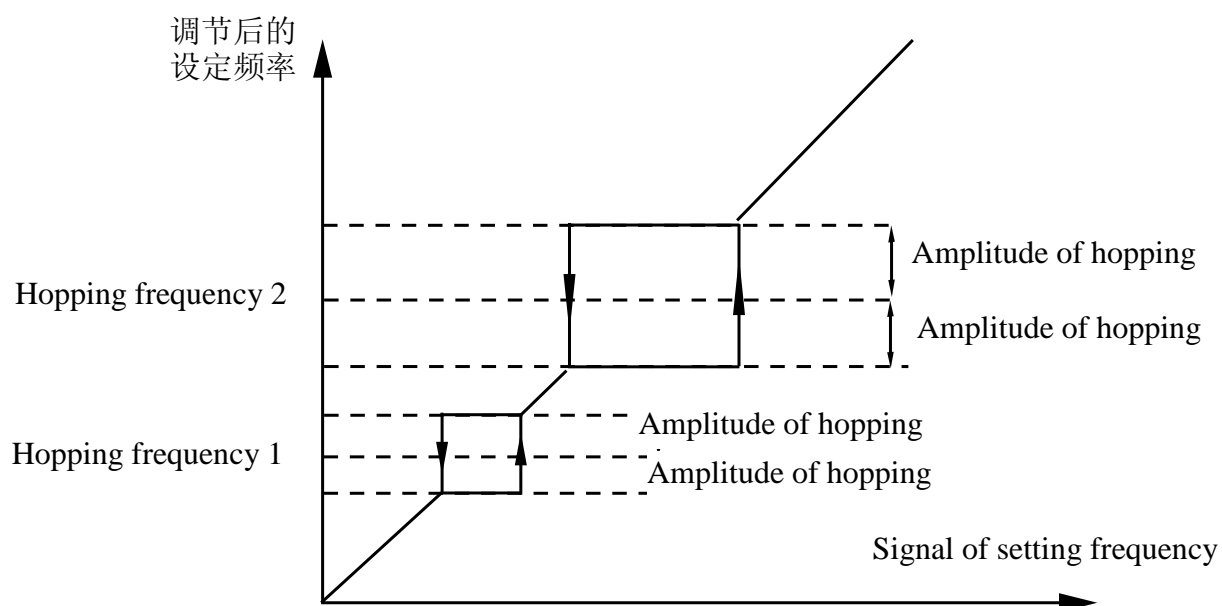
Jog deceleration time indicates the time for converter to decelerate from maximum frequency (P0-08) to 0 Hz.

PA-08	Hopping frequency1	0.0~Upper limiting frequency (P0-09)	Default: 0.0Hz
PA-09	Hopping frequency2	0.0~Upper limiting frequency (P0-09)	Default: 0.0Hz
PA-10	Amplitude of Hopping frequency	0.0~Upper limiting frequency (P0-09)	Default: 0.0Hz

Actual operating frequency will be held at the boundary of hopping frequency which is closed to preset frequency when preset frequency is within the range of hopping frequency.

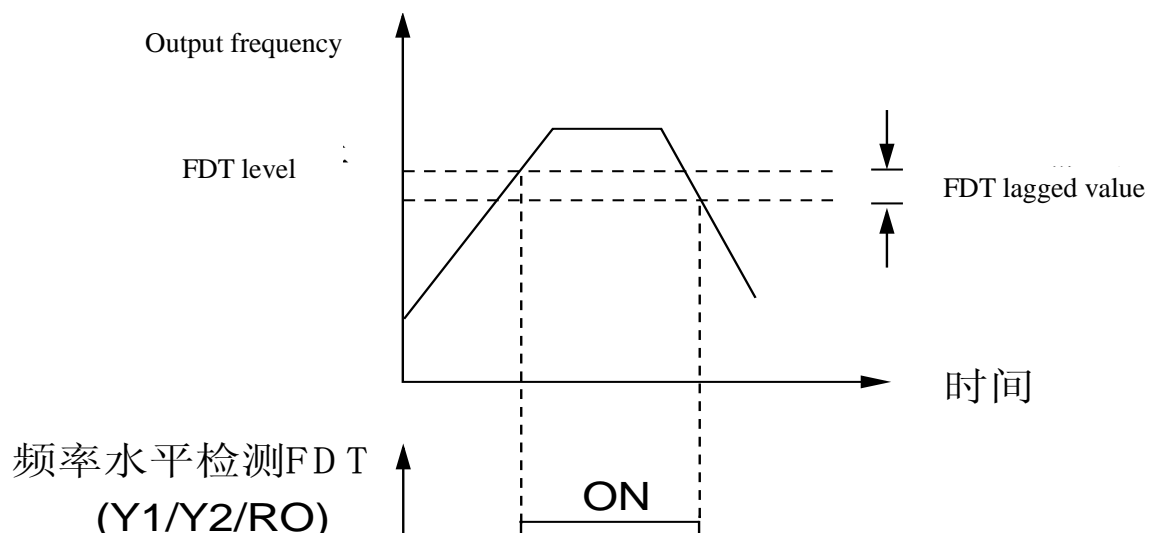
Converter can be kept away from the resonance point of load by the setting of hopping frequency. Two hopping points of frequency are set for this converter; if both of these two points are set as zero, this function will be disabled.

Setting frequency
after regulation



PA-11	FDT level value	0.0~Upper limiting frequency (P0-09)	Default: 0.0Hz
PA-12	FDT lagged value	0.0~FDT level value (PA-11)	Default: 0.0Hz

These two parameters above are mainly applied to the setting of the detected value of output frequency (PA-11) as well as lagged value obtained after output is enabled.



Time

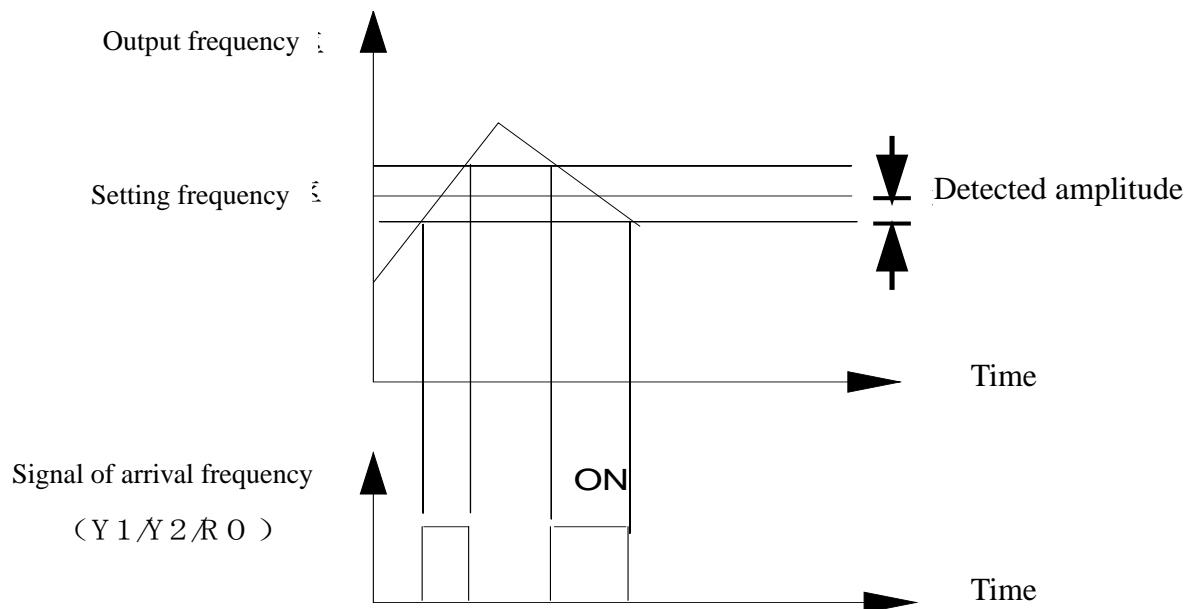
Frequency level detection FDT

Time

PA-13	Amplitude of detected frequency FAR	0.0~Upper limiting frequency (P0-09)	Default: 0.0Hz
--------------	-------------------------------------	--------------------------------------	----------------

It's mainly applied to the setting of amplitude detection for detected frequency.

Please refer to the following graph:



PA-14	Setting count value	1~65535	Default: 1000
PA-15	Specified count value	1~65535	Default: 1000

Counts of pulse signal or switching signal can be input by the counter which is installed in the multi-functional DI terminal.

When count value reaches up to preset count value, signal will be output by DO terminal to prove that preset count value is reached.

When count value reaches up to specified count value, signal will be output by DO

terminal to prove that specified count value is reached. Counter will not stop until it reaches up to “setting count value”

Specified count value PA-15 must be no more than setting count value PA-14.

PA-16	Underclocking function for overload	0: Disabled 1: Enabled	Default: 1
--------------	---	---------------------------	------------

Converter’s current will also be increased as abnormal load transient boosts instantaneously; if no action is taken in time, stripping may be caused by over current.

Underclocking function for overload: if instantaneous current is increased up to the maximum, output frequency of converter must be decreased properly to restrain current from being increased so that converter can be prevented from stripping caused by instantaneous overload.

Chapter 7 Fault Correcting

7-1 Malfunction and Solutions

Fault indication	Code	Fault Type	Fault cause	Solutions
LU	3	Under voltage	Abnormal power supply or loose contact	Input voltage and wiring should be checked
OU	4	Overvoltage	1、 Input voltage 2、 Rapid deceleration 3、 Excessive inertia load	1、 check input voltage 2、 increase deceleration time 3、 select dynamic braking components
OC	6	Over current	1、 mismatch of capacity 2、 low voltage of grid 3、 Rapid acceleration and deceleration 4、 high torque of inertia load 5、 abnormal load	1、 select converter with large capacity 2、 check power source and wiring 3、 Increase Acc-Dec time 4、 select applicable braking parts 5、 detect and reduce load changing
OL	5	Overload (converter)	1、 please refer to fault cause of over current(OC) 2、 overload(motor) 3、 inapplicable setting of V/F curve	1、 please refer to solutions for over current(OC) 2、 reduce motor load 3、 reset parameters
OL1	15	Overload (motor)	1、 low voltage of grid 2、 Excessive motor stalling or load changing 3、 inapplicable setting of V/F curve, rated current or critical point of overload protection	1、 check the voltage of grid 2、 check motor load 3、 reset parameters
SC	9	short-circuit output	1、 please refer to fault cause of over current(OC) 2、 short circuit of output terminal(U,V,W) or earth terminal 3、 loose plug-in units or wiring of control panel 4、 damages of power module or other parts	1、 please refer to solutions for over current(OC) 2、 check the state of insulation(motor & cable) 3、 check the connection of plug-in units 4、 seek technical support for damages
SPI	7	Input Failure	default phase of power source R,S,T	1、 check power source and its voltage 2、 check the connection of

				power line
SPO	8	Output failure	1、 default phase of output terminals U, V, W 2、 unsymmetrical three-phase load	1、 check the connection of output line 2、 check motor and its cables
OH	13	Overheat	1、 high ambient temperature 2、 obstruction of ventilation duct or damage of cooling fan 3、 excessive motor load	1、 Lower the ambient temperature 2、 Clear the ventilation duct and replace the cooling fan 3、 Reduce motor load or carrier frequency
PIE	12	PI fault	No detection of PI feedback signal for a certain time	Check on PI feedback signal and connection
EF	11	External fault	input terminal for external fault signal is enabled	Check the input of external devices
EEP	1	EEPROM fault	1. R/W errors of parameter 2. Damage of EEPROM	1. factory reset 2. seek technical support for damages
NCE	16	Contactor fault	1、 low voltage of grid 2、 damage of contactor 3、 the other damaged circuit	1、 check the voltage of grid 2、 replace the contactor of major loop 3、 seek technical support for damages
OPSE	10	System failure	Severe interference from external factors, e.g. noise	install additional filter or seek technical support for damages
CF	20	The current detecting signal failure	1, the current sensor is damaged 2, signal lines, poor contact 3, other line fault	1, change the current sensor 2, check the signal lines 3, seeking services

7-2 Common Faults and Processing Schemes

If the following situations are met during the application of converter; please refer to the instructions below:

- No information display after power on

Please confirm whether the voltage of power source is compatible with the rated voltage of converter.

Please check whether three-phase rectifier bridge is in good condition; if it's damaged, please seek for technical support.

Please check if power indicator is on or not; if it's off, malfunction is mainly caused by abnormal rectifier and buffer resistance; if it's on, malfunction is mainly caused by switching power supply. Meanwhile, please seek for technical support.

- Air switch of power source trips when power on

Please check whether power source is grounded or short-circuited; please solve it accordingly.

Please check whether rectifier bridge is burned; if it's damaged, please seek for technical support.

- **Motor doesn't start running after converter is started**

Please check whether there is three-phase symmetrical output among U, V, W. If there is, motor or its circuit is damaged mostly; or stalling may be caused by mechanical problem. please solve it accordingly.

If three-phase output is unsymmetrical, then driver board or output module of converter may be damaged. Please seek for technical support.

If there is output voltage, then driver board or output module may also be damaged. Please also seek for technical support.

- **Air switch of power source trips while running**

Please check whether output modules between phase and phase are short-circuited; if there is short circuit, please seek for technical support.

Please check whether motor lines are short-circuited or grounded; if they are, please solve it accordingly.

If stripping take places sometimes, not regularly; and there is a long distance between motor and converter, please take the installation of additional AC reactor into consideration.

Chapter 8 Maintenance

Only the qualified engineer is allowed to conduct maintenance for converter; please pay attention to the following precautions:

- Maintenance must be conducted by qualified engineer in specified way;
- Only when converter is shut down for 5 minutes can maintenance be conducted;
- Do not touch the components on the PCB directly; otherwise, components can be damaged by static easily.
- Make sure that all the screws are fastened after the maintenance.

8-1 Daily Maintenance and Upkeep

Affected by environmental conditions(e.g. temperature, humidity or smog) and aging of internal components, converter may malfunction. Therefore, daily inspection and maintenance on converter must conducted during the process of storage and application. For the detailed information of daily inspection and maintenance, please refer to the following table:

Items	examination period		check points	criterion and maintenance
	non-periodical	regular		
Environmental conditions	√		1. temperature & humidity 2. dust & mist 3. Gas	1. temperature <40℃ , humidity < 90%, no frost 2. No odor, No flammable or explosive gas
Cooling system		√	1.installation environment 2. built-in fan	1. good ventilation, no obstruction of ventilation duct 2. normal operation of built-in fan, no abnormal noise
Converter	√		1. vibration and temperature rise 2. noise 3. dust or impurity	1. stable vibration, normal blast temperature 2. No abnormal noise or odor 3. remove dust by dry compressed

			4. lead and terminals	air 4. no loose screws
motor	√		1.vibration and temperature rise 2. noise	1. stable operation and normal temperature 2. No malfunction or abnormal noise
I/O parameters	√		1. input voltage 2. output current	1. Input voltage is within specified range 2. output current is lower than rated value

8-2 Inspection and replacement of damageable parts

As for some of internal components, abrasion or performance degradation may be caused during use. To ensure stable and reliable operation, preventive maintenance on converter must be conducted. If necessary, please replace them:

Fan must be replaced after more than 20,000 hours' running

Electrolytic capacitor must be replaced after 30,000~40, 000 hours' running

8-3 Storage

This product can't be taken out from box until it's about to be installed. To ensure that it's still valid for warranty and available for maintenance in the future during the period of storage, please pay attention to the following points:

- converter must be stored in a dry place where there is no dust;
- ambient temperature must be within the range between -20°C and $+60^{\circ}\text{C}$;
- relative humidity must be within the range between 0% and 95%; no condensation is permitted;
- it must be protected from caustic gas or liquid;
- it must be packed properly and put on the shelf or desk.

8-4 Product Warranty

Any of the following situations will be our company's responsibility, which will be considered and guaranteed:

- The warranty period for this product is 18months but only 12 months for final buyer. During the period, any damage or fault without any wrong operation will be our responsibility to fix, which is free of charge. Maintenance fee will be charged accordingly if warranty expires.

- Regarding the faults caused by the following points, extra fee will need to be charged as service fee:

- 1) fault caused by faulty operation which is not in conformity with manual or specification
- 2) fault caused by unauthorized maintenance modification;
- 3) damage caused during the transportation or improper safekeeping;
- 4) fault caused by misuse failure

5) As for the damages caused by fire, salt corrosion, gaseous corrosion, earthquake, storm, flood, thunder strike, abnormal voltage and other irresistible factor, despite of the expiration of warranty, any compensable maintenance service will be provided by our company for good.

Chapter 9 Communication Protocol

Modbus protocol is the main communication method applied in KDE200 series converter with RS485 interfaces, which is compliant with International Communication Standards. Centralized control can be implemented by PC/PLC as well as superior controller to adapt specific requirements for applications, including setting of control command, operating frequency, modification of parameters for relevant function code, monitoring of operating status or malfunction.

9.1 Protocol Content

Modbus, also known as serial communication protocol, has defined its frames and format during the asynchronous transmission, including the format of polling to the host, broadcast frames and response frames to slave controller. The frames generated by the host included slave address/broadcast address, executive command, data & error correction; and the response of the slave controller has the similar frames as the host, including confirmation of instructions, data feedback and error correction. If any error happens when the slave controller receives the frames, or any instruction requested by the host can't be done, it will generate a malfunction frame and send feedback to the host.

9.1.1 Application mode

KDE200 series converter is compatible with control network equipped with RS485 bus which has single host & multiple slave controllers.

9.1.2 Bus Structure

(1) Hardware interface

RS485 hardware interface

(2) Transmission mode

Serial & asynchronous, half-duplex transmission -- TXD and RXD can be done at the same time by either the host or the slave controller separately, which means there are only one sender and one receiver at a time. Data will be transmitted frame by frame in the format of message during the serial & asynchronous communication.

(3) System with single host & multiple slave controllers

The range of slave address should be 1~127; the number Zero stands for broadcast communication address. Every single slave address on the Internet is unique, which is the foundation of Modbus serial communication.

9.2 Protocol Introductions

The protocol of KDE200 Series Converter is a kind of serial & asynchronous communication protocol with principal and subordinate Modbus; there is only one device(host) could set up protocol (named "query /command"), and the other devices(slave) can only response to the host's "query /command" by sending data, or issue commands/instructions according to the "query /command" from the host. The host herein mainly refers to personal computer, industrial control facility or Programmable Logic Controller (PLC); and the slave herein mainly refers to KDE200 Series Converter or the other control facilities with similar/same communication protocol. The host can not only communicate with a certain slave controller independently but also send broadcast message to all the slave controllers. As to any independent access to the host's "query /command", a message (called response) must be sent out from the slave controller; however, regarding the broadcast message issued by the host, it's not necessary for the slave controller to send feedback to the host.

9.3 Frame Structure

The data format of Modbus communication protocol applied in the KDE200 Series Converter is RTU mode (Remote Terminal Unit)

In the RTU mode, the format of each byte is as follow: encoding system -- 8-bit binary system, there are two hexadecimal characters included in every 8-bit frame (hexadecimal characters include 0~9 & A~F). The transmission of new frame will always be restarted with a interval of 3.5 bytes transmission time. When it's connected with the Internet of which transmission rate is calculated by Baud rate, 3.5-byte transmission time is easy to be controlled. The data fields of transmission will be sent in sequence as below: slave address - operating command code - data & CRC check word; and transmission byte of each field are hexadecimal (0~9, A~F). The networking devices will always monitor the operation of communication bus; when the first domain (address information) is received, it will be confirmed again by each networking device; when the transmission of last byte is done, there will be a interval of 3.5 bytes transmission time to indentify the end of this frame. After that, transmission of new frame will be started again.

Frame Format of RTU Data					
	MODBUS Message				
Initiate: a interval of at least 3.5 bytes	Slave address	Function code	Data	Verification	Terminate: a interval of at least 3.5 bytes

A frame message must be transmitted in a consecutive data stream; if the interval is more than 1.5-byte transmission time before transmission of the whole frame is finished, those incomplete messages will be cleared by the receiver which will take the next byte as part of address field of new frame by mistake; likewise, if the interval is less than 3.5-byte transmission time, the receiver will identify it as the extension of last frame. Because of disorder of frames, CRC value will be incorrect, which may result in malfunction.

Standard Structure of RUT Frame

Frame header	T1-T2-T3-T4 (3.5-byte transmission time)
Slave address field	Communication address: 0~147(decimal system) / (Zero stands for broadcast communication address)
Function domain (CMD)	0x03: reading parameters of slave controller 0x06: programming parameters of slave controller
Data field ENTER (N-1) ... ENTER (0)	2*N-byte data is not only the main content of communication but also the core of data exchange during the communication.
Checksum	estimated value: CRC value (16BIT)
Frame ending	T1-T2-T3-T4 (3.5-byte transmission time)

9.4 Command code & data description

9.4.1 Format of No.1 address for Setting as follows, setting frequency 50Hz (PO-03)

Superior host command:

Frame header	3.5-byte interval
Address	0x01
Function code	0x06
Register address	0x0003
Register information	0x01F4
Checksum	0x79DD
END	3.5-byte interval

Converter's response:

Frame header	3.5-byte interval
Address	0x01
Function code	0x06
Register address	0x0003
Register information	0x01F4
Checksum	0x79DD
END	3.5-byte interval

9.4.2 Format of No.1 address for reading as follows, setting frequency (PO-03)

Note: register number must be one only when reading

Superior host command:

Frame header	3.5-byte interval
Address	0x01
Function code	0x03
Register address	0x0003
Register number	0x0001
Checksum	0x740A
END	3.5-byte interval

Converter's response:

Frame header	3.5-byte interval
Address	0x01
Function code	0x03
Register address	0x02
Register information	0x01F4
Checksum	0xB853
END	3.5-byte interval

9.4.3 Frame format of response error as follows, setting frequency 60Hz (PO-03)

Type of error:

01H -- data address overrun

02H -- number of data overrun & read-in data content exceeding bounds(ceiling & floor)

03H -- Operating, no read-in data are permitted

Superior host command:

Frame header	3.5-byte interval
Address	0x01
Function code	0x06
Register address	0x0003
Register information	0x0258
Checksum	0x7950
END	3.5-byte interval

Converter's response:

Frame header	3.5-byte interval
Address	0x01
Function code	0x86
Error code	0x02
Checksum	0xC3A1
END	3.5-byte interval

9.4.4 CRC Mode

RTU frame format is mainly applied to CRC (Cyclical Redundancy Check), error detecting field based on CRC is included in the message. CRC domain can detect all the information of message, which is two bytes with 16-bit binary value included. It will be added into the message after the calculation of transmission devices. The receiver will recalculate the CRC receiving the message, and compare it with the values in the CRC domain received by devices; if the CRC value is not equivalent to another one, it proves that there is error in the transmission.

CRC will write 0xFFFF in superior host, and call a program to process the consecutive 8 bytes in the message as well as the values in the register. Only 8-bit data of each character is valid to CRC, the others are all invalid, including start bit, stop bit and parity check bit.

During the operation of CRC, each of 8-bit character is exclusive(XOR) with register content separately; result will be inclined to the least significant bit(LSB) while the most significant bit will be filled with Zero. LSB will be extracted from the data for checking; if LSB is one, register will be exclusive(XOR) with preset value separately; if LSB is zero, calculation will not be conducted. This instruction of process will repeat for 8 times; when it comes to the last bit (8th bit), the next 8-bit bytes will be exclusive(XOR) with register value again. The final value in the register is the CRC value after the calculations of all the bytes in the message.

When CRC is added into the message, lower byte will be added first, then the high byte. The simple function of CRC is as follows:

```
unsigned int crc_chk_value (unsigned char *data_value,unsigned char length) {
    unsigned int crc_value=0xFFFF;
    int i;
    while (length-->0) {
        crc_value^=*data_value++;
        for (i=0;i<8;i++) {
            if (crc_value&0x0001)
            {
                crc_value= (crc_value>>1)
                ^0xa001;
            }
            else
            {
                crc_value= (crc_value>>1)
            }
        }
    }
    return (crc_value) ;
}
```

9.5 Read-write rules of parameter address for function code

This part defines the address of communication data; it's mainly used to control the operation of converter, get access to the status information as well as relevant function parameter setting. It helps converter to find the corresponding communication address for the parameter by the serial number of function code. Note: all the serial numbers(S/N) of function code's address is decimal number.

(1) Expression rules of parameter address for function code

The corresponding communication address for all the parameters between P0-00 and PA-26 is 0~191.

For example:

Register address	Address S/N	Corresponding parameters
0x00	0	P0-00
0x01	1	P0-01
0x02	2	P0-02
.....
0x11	17	P0-17
0x12	18	P1-00
0x13	19	P1-01
.....
0x18	24	P1-06

Register address	Address S/N	Corresponding parameters
0x19	25	P2-00
0x20	26	P2-01
.....
0x25	37	P2-12
0x26	38	P3-00
0x27	39	P3-01
.....
0x32	50	P3-12
0x33	51	P4-00

Register address	Address S/N	Corresponding parameters
0x34	52	P4-01
.....
0x45	69	P4-18
0x46	70	P5-00
0x47	71	P5-01
.....
0x64	100	P5-30
0x65	101	P6-00
0x66	102	P6-01
.....
0x6D	109	P6-08
0x6E	110	P7-00
0x6F	111	P7-01
.....
0x7D	125	P7-15

Register address	Address S/N	Corresponding parameters
0x7E	126	P8-00
0x7F	127	P8-01
.....
0x92	146	P8-20
0x93	147	P9-00
0x94	148	P9-01
.....
0xA4	164	P9-17
0xA5	165	PA-00
0xA6	166	PA-01
.....
0xBF	191	PA-26

(2) Descriptions of the other functions' address

Parameters address monitoring:

Register address	Address S/N	Data description	Register address	Address S/N	Data description
0xDC	220	Setting frequency	0xE6	230	PI preset value
0xDD	221	Output frequency	0xE7	231	PI feedback value
0xDE	222	Output current	0xE8	232	Run time
0xDF	223	Busbar voltage	0xE9	233	Input interface
0xE0	224	Motor speed	0xEA	234	Output interface
0xE1	225	Percentage of current	0xEB	235	Rated power
0xE2	226	IGBT temperature	0xEC	236	Compensation
0xE3	227	Output voltage	0xED	237	Compensation voltage
0xE4	228	Output power	0xEE	238	Phase angle
0xE5	229	Count value	0xEF	239	Load factors

Control command

(valid when P0-02 is changed into 3)

Register address	Address S/N	Data description
0xC8	200	1: FWD run
		2: FWD jogging
		5: REV run
		6: REV jogging
		8: Stop
		16: Regular stopping
		32: Reset

Status of Converter

Register address	Address S/N	Data description
0xF0	240	0: Operating
		1: FWD running
		2: REV running
		3: Malfunctioning

Fault address

Register address	Address S/N	Data description	
0xF1	241	1: Storage fault	10: System fault
		3: Undervoltage	11: External fault
		4: Overvoltage	12: PI fault
		5: Overload	13: Overtemperature
		6: Overcurrent	14: Overcurrent
		7: Input default phase	15: Motor overload
		8: Output default phase	16: Contactor off
		9: Output short circuit	20: Signal failure of current detection

9.6 Parameter description of communication

Baud rate	Factory default	9600
-----------	-----------------	------

The parameter above is used to set transmission rate of the data between superior controller and converter. Note: the Baud rate of superior controller and converter should be the same; otherwise, communication cannot be conducted.

Data format	Factory default	No checking: 8-N-1
-------------	-----------------	--------------------

The data format of superior controller and converter should be the same; otherwise, communication cannot be conducted.

P0-15	Local address	Factory default	1
	Setting range	0-127 (Zero stands for broadcast address)	

When local address is set to be zero (a.k.a. broadcast address), broadcast function will be activated on the superior controller. The local address is unique (except broadcast address), which is the foundation/premise to conduct point-to-point communication between superior controller and converter.

Chapter 10 Appendix

10-1 List of braking resistor

If controlled motor decelerates too fast, or load jittering of motor is too fast while converter is running, its electromotive force will charge the internal capacitors of converter through converter's reverse function, which will rise the voltage of power module and damage converter. However, this will be restrained by converter's internal control according to the condition of loading; additional braking resistor needs to be installed externally to release the power in time when braking performance doesn't meet customers' requirements.

External braking resistor works by consuming energy which will be consumed completely by power braking resistor; therefore, power and resistance of braking resistor must be applicable and effective. Braking resistors whose power and resistance value are as followed are recommended to be applied to this converter. According to the condition of loading, value can be changed properly; but it must be no less than the minimum of this converter

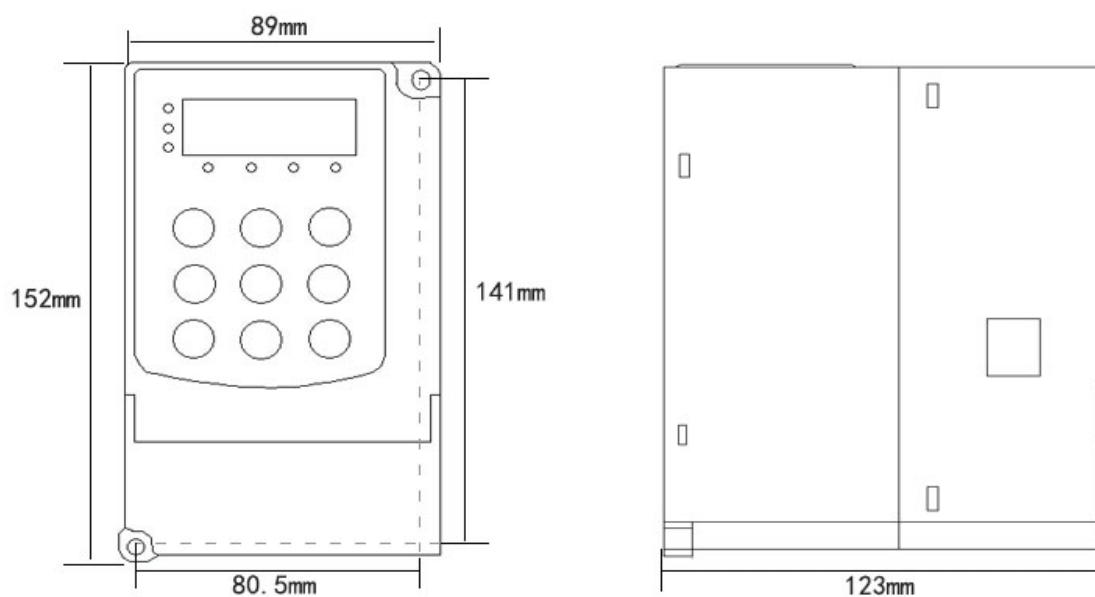
Converter power	Recommended resistance	Minimum resistance
KDE200-R75GS2	80W 150 Ω	80 Ω
KDE200-1R5GS2	200W 100 Ω	55 Ω
KDE200-2R2GS2	200W 70 Ω	35 Ω
KDE200-R75GT4	150W 400 Ω	260 Ω
KDE200-1R5GT4	200W 300 Ω	200 Ω
KDE200-2R2GT4	250W 200 Ω	150 Ω
KDE200-3R7GT4	300W 200 Ω	130 Ω

Due to the energy consumption of braking resistor, a mass of heat may be generated if it keeps braking frequently; therefore, safety and inflammability of the surrounding must be taken into consideration

10-2 Technical specification

Rated power kW	0.7	1.5	2.2	0.7	1.5	2.2	3.7	POWER
Output current A	5	7	11	2.5	3.7	5.1	9	CURRENT
rated voltage V	Single-phase 220V			Three-phase 380V				
rated output frequency				The maximum can reach up to 400Hz by programming				
Power supply	Rated input voltage/frequency			one-phase/three-phase 220V 50Hz/60HZ; three-phase 380V 50Hz/60HZ;				
	Allowed voltage fluctuation			+15% , -15%				
	Allowed frequency fluctuation			±5%				
Control feature	Control method			Optimize the control of space vector SVPWM				
	control range of frequency			0.1~400.0Hz				
	Frequency precision			Digital setting: 0.01% analog instruction: 0.1% (max. frequency)				
	Frequency resolution			Digital command: 0.1Hz analog instruction: 0.1Hz				
	Acc-Dec time			0.0 ~ 3600s(separate setting of acceleration/deceleration time) four kinds of acceleration/deceleration time are optional				
	multispeed running			Built-in PLC programming is running in multiple speeds multispeed running is controlled by external multispeed terminals				
	Built-in PI			automatic control system can be set up easily				
	Built-in counter			With the combination of built-in PLC, automatically-controlled production line can be achieved				
	overload capacity			model G -- 150% rated current per minute model P -- 120% rated current per minute				
	Braking torque			About 20% (it can reach up to 150% whenever there is braking resistance)				
	V/f mode			Three preset V/f model and V/f model which can program arbitrarily				
	Automatic energy-efficient operation			Energy-efficient operation can be achieved by changing V/F curve automatically according the condition of loading				

	Automatic voltage regulation (AVR)	it can stabilize output voltage automatically whenever there is change for the voltage of grid
Running function	preset running instruction	preset panel and preset external terminal
	Setting of frequency	Digital setting setting of analog voltage setting of analog current
	Input signal	FDW/REV instruction Jog option multispeed control regular stopping external fault
	Output signal	Failure alarm output (250V/2A contact) open-collector output
Protection function		Over current、 overvoltage、 under voltage、 overheating、 overload、 default phase、 anti-stall voltage/current
Display		Parameter setting、 information display、 fault indication
environmental conditions	operating environment	Temperature $-10^{\circ}\text{C} \sim +40^{\circ}\text{C}$ Humidity $<90\% \text{ RH}$ No condensation
	operating situation	Indoor (it must be protected from corrosive gas or dust) Altitude: no more than 1000 meter
	storage temperature	$-20^{\circ}\text{C} \sim +60^{\circ}\text{C}$
	vibration	Less than $5.9 \text{ m/s}^2(0.6\text{g})$



Model	Mounting Dimension		Dimension			Pore Diameter(mm)
	length (mm)	wide (mm)	length (mm)	wide (mm)	high (mm)	
0.75G~3.7G	141	80.5	152	89	123	5.2
0.75G~3.7G keyboard installation dimensions: length = 115 mm width = 115 mm						

Quick Debugging/Quick set up instructions

